

RECOVERY PROCESSES AND DYNAMICS IN SINGLE AND INTERDEPENDENT NETWORKS

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Outline



1.1 Single networks: phase diagram



1.2 Phase flipping in single networks



2.1 Interacting networks: phase diagram



2.2 Problem of optimal repairing



2.3 Dynamics of interacting networks

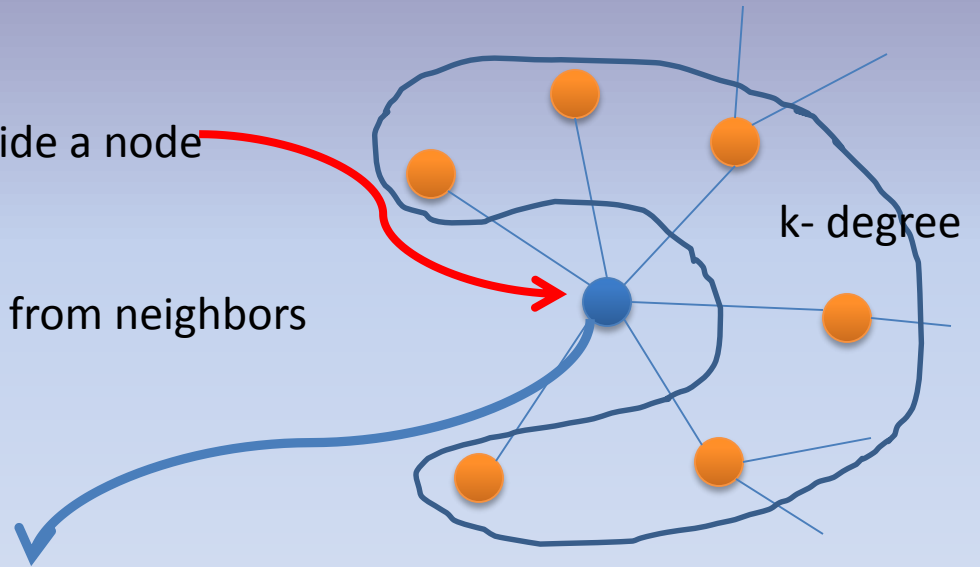
1.1 Single networks: phase diagram

SINGLE NETWORKS: FRS MODEL

- Each node in a network can be **active** or **failed**.
- We suppose there are TWO possible reasons for the nodes' failures: INTERNAL and EXTERNAL.

1. INTERNAL failure: intrinsic reasons inside a node

2. EXTERNAL failure: damage “imported” from neighbors
-->damage spread.



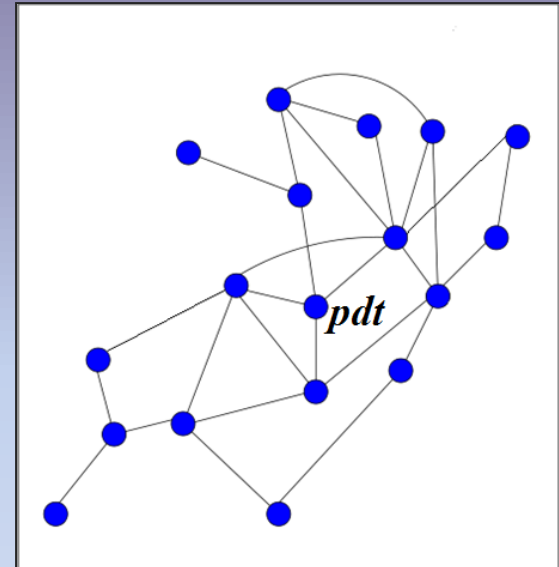
3. RECOVERY: A node can also **recover** from each kind of failure.

LET'S SPECIFY/MODEL THE RULES.

1. INTERNAL FAILURES

p- rate of internal failures (per unit time, for each node).
During interval dt , there is probability pdt that the node fails.

Recovery: A node *recovers* from an internal failure after a time period τ .



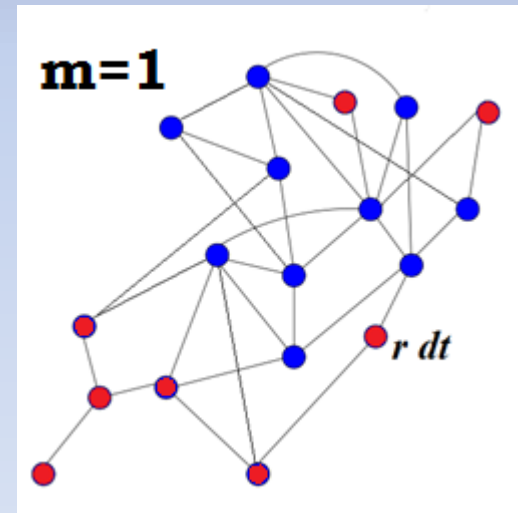
2. EXTERNAL FAILURES – if the neighborhood of a node is too damaged

IF: “CRITICALLY DAMAGED neighborhood”: **less than or equal to m active neighbors**,
where **m** is a fixed treshold parameter.

THEN: There is a probability $r dt$ that the node will experience externally-induced failure during dt .

r - external failure rate

A node recovers from an external failure after time τ' .



FAILURE TYPE	RULE	RECOVERY
Internal failure	With rate p on each node	After time τ
External failure	IF($\leq m$ active neighbors) THEN Extra rate r on each node	After time τ'

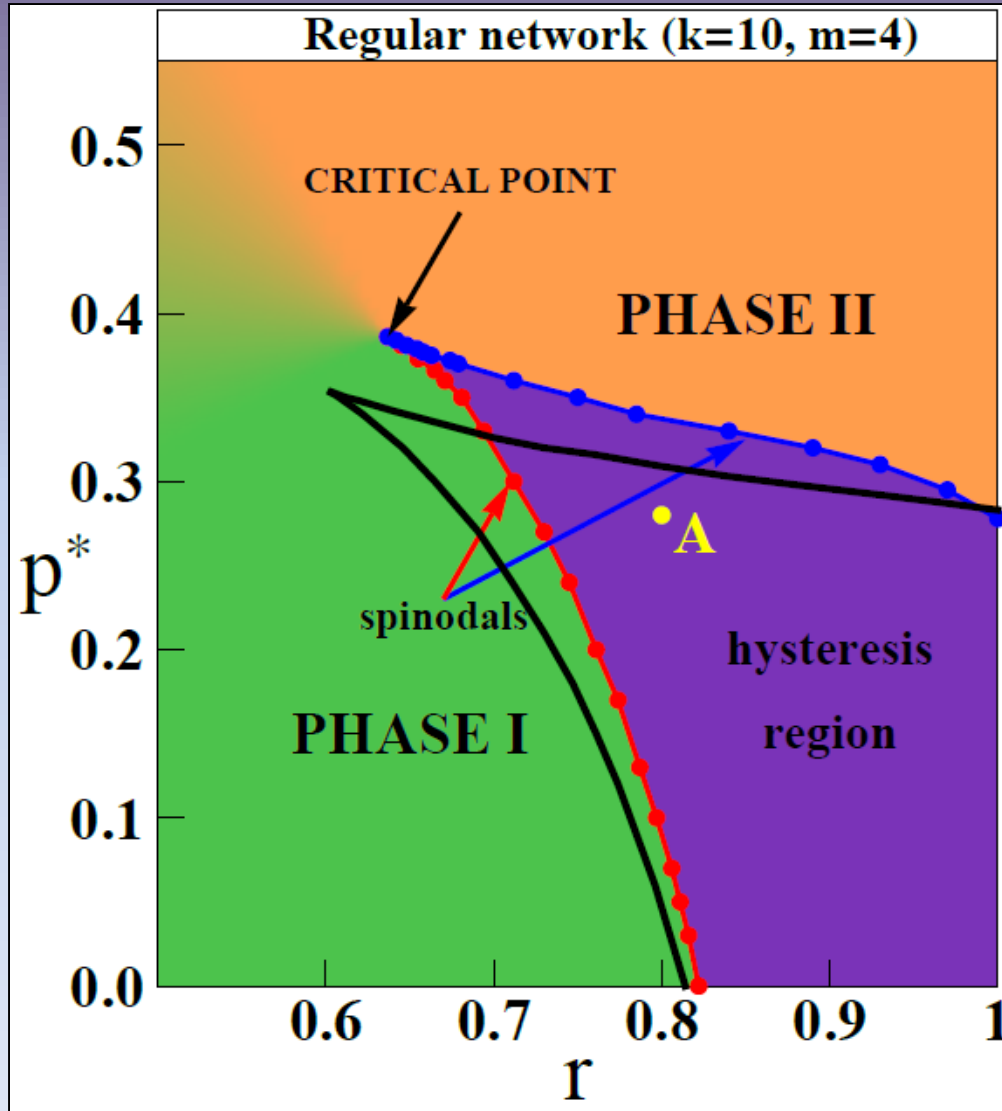
Out of these 5 parameters, we fix three of them:
 $m=4$, $\tau=100$ and $\tau'=1$.

We let (p,r) to vary.

It turns out it is convenient to define $p^*=exp(-p\tau)$.
 So we use (p^*,r) instead of (p,r) .

We measure activity Z of the network as a function of (p^*,r) .

Phase diagram (single network, random regular)



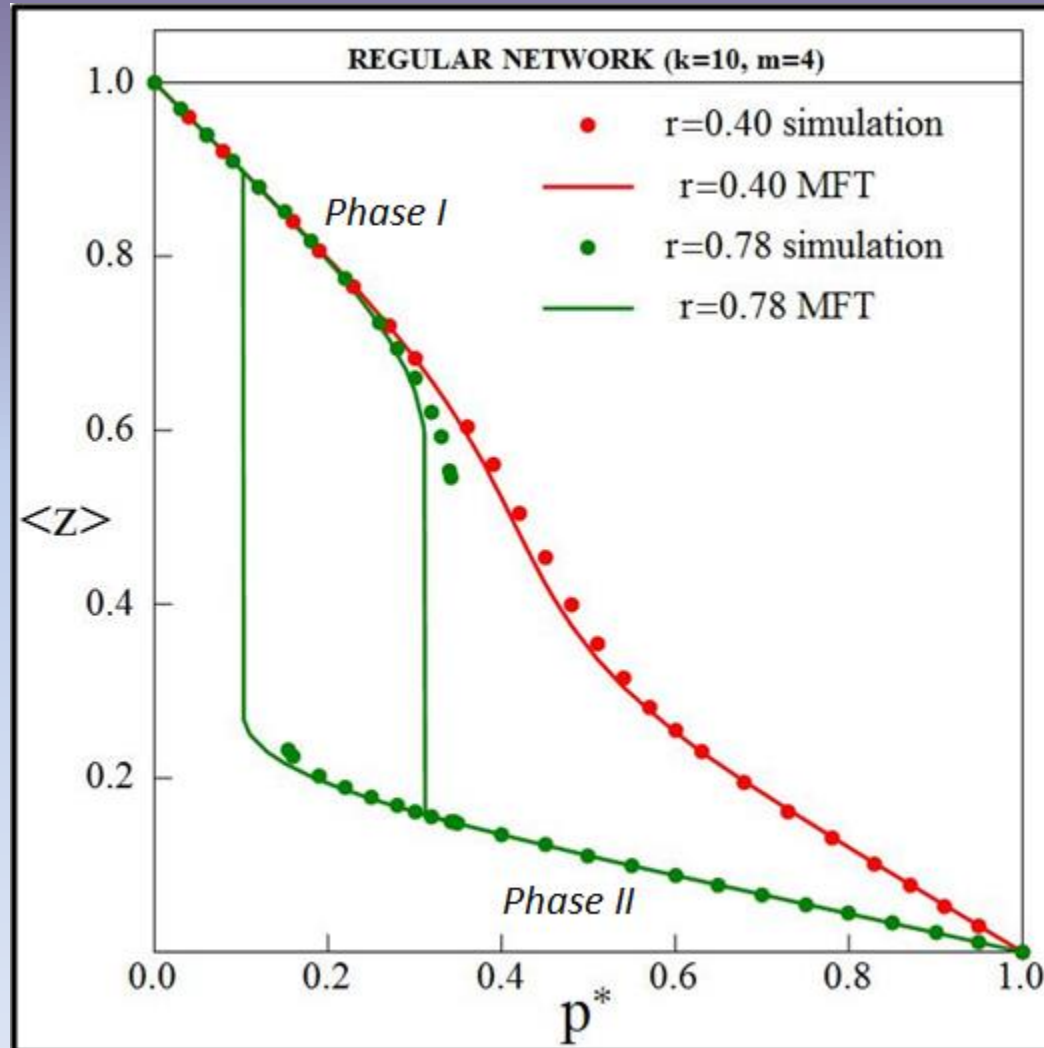
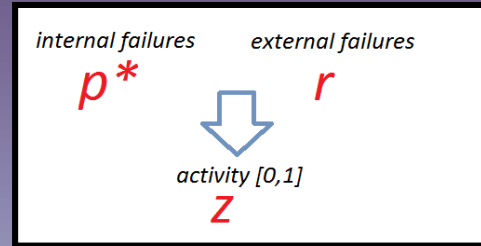
GREEN; High activity Z
ORANGE: Low activity Z

In the hysteresis region both phases exist, depending on the initial conditions or the memory/past of the system.

Blue line: critical line (spinodal) for the abrupt transition $I \rightarrow II$

Red line: critical line (spinodal) for the abrupt transition $II \rightarrow I$

Model simulation [Random regular networks]

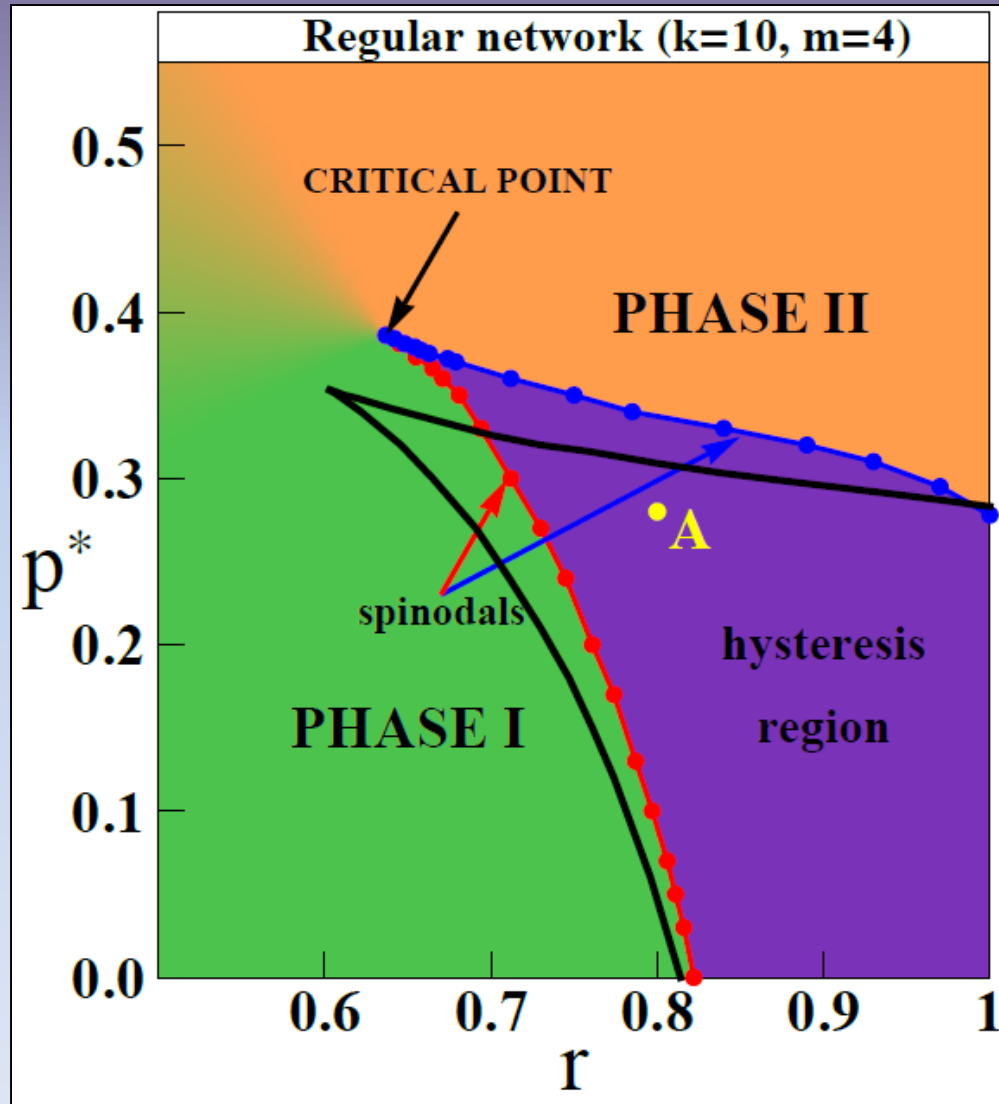


$\langle Z \rangle$ - average fraction of active nodes (Z fluctuates)

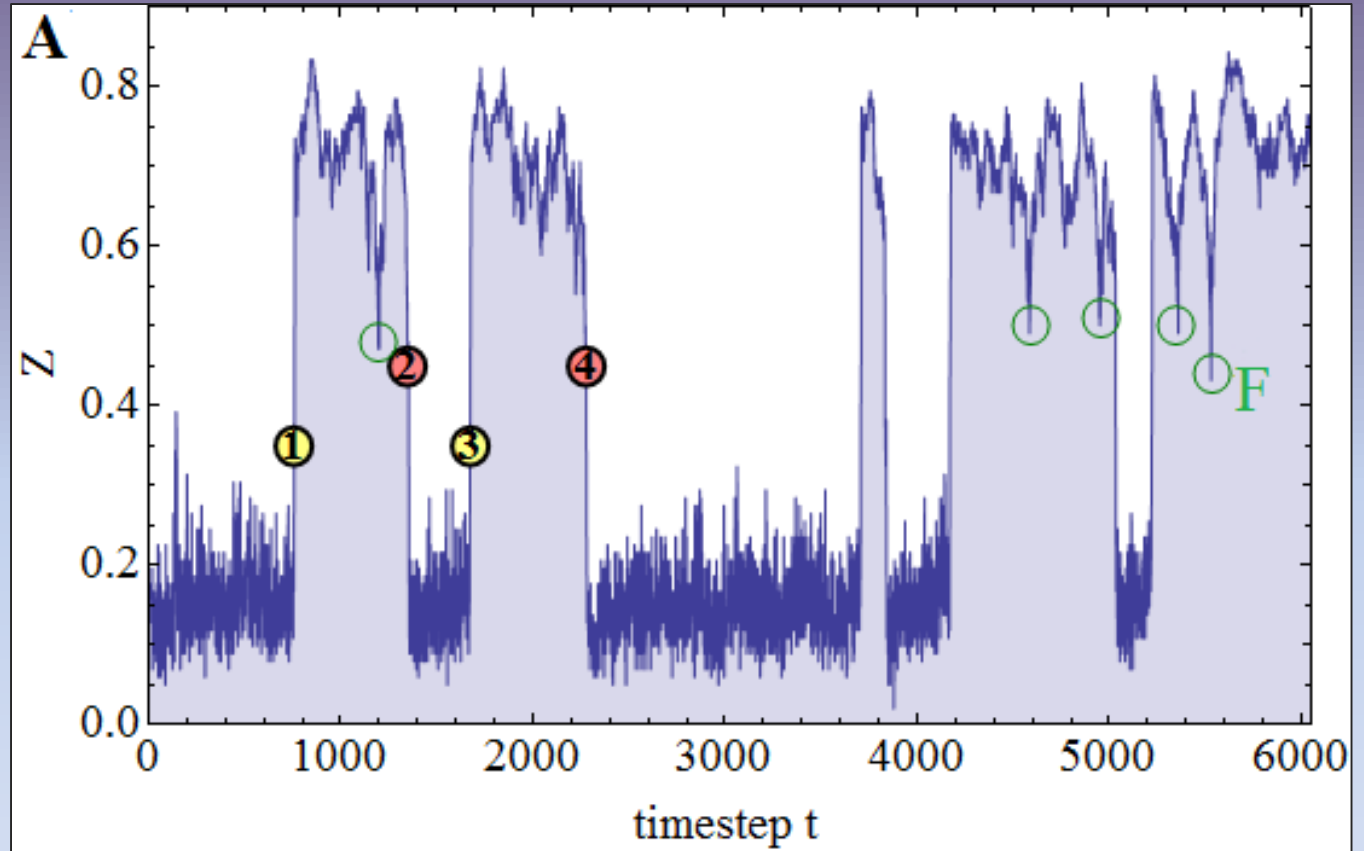
For some values of r we have a hysteresis loop.

1.2 Phase flipping in single networks

Let's pick point A, take a small system $N=100$, and run the simulation



Finite size effects

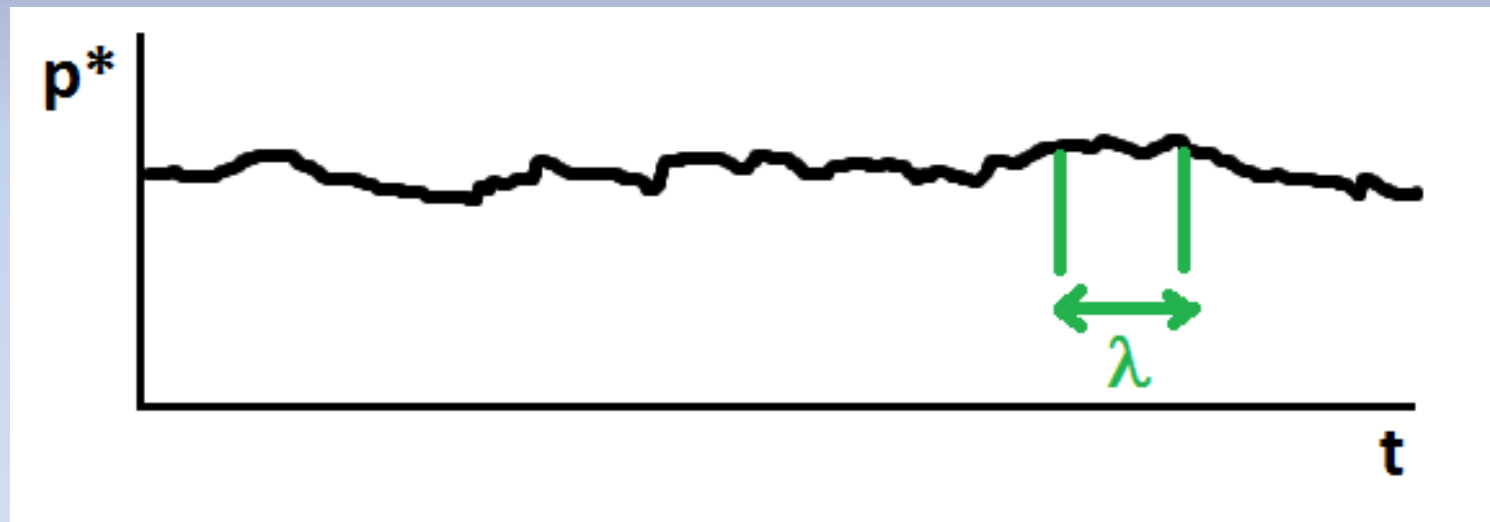


→ Sudden transitions

1. Why?

2. Is there any forewarning?

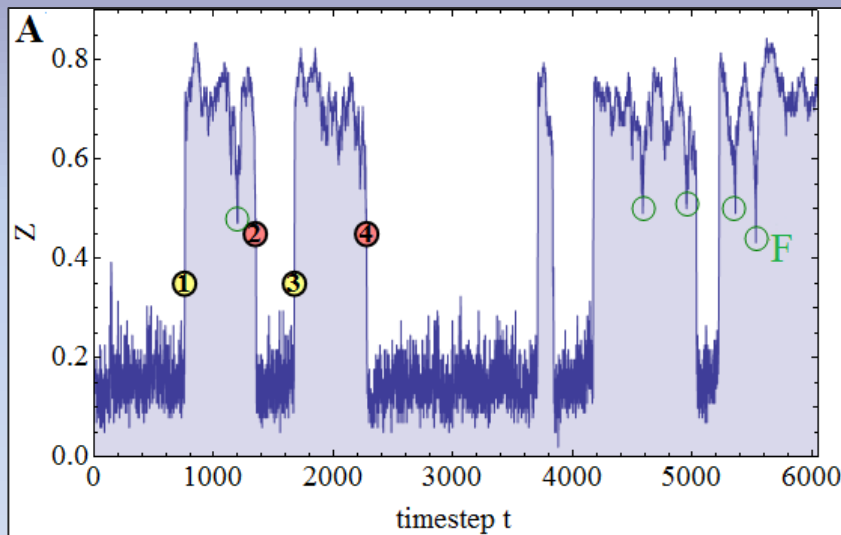
(Remember : Z = Fraction of active nodes)



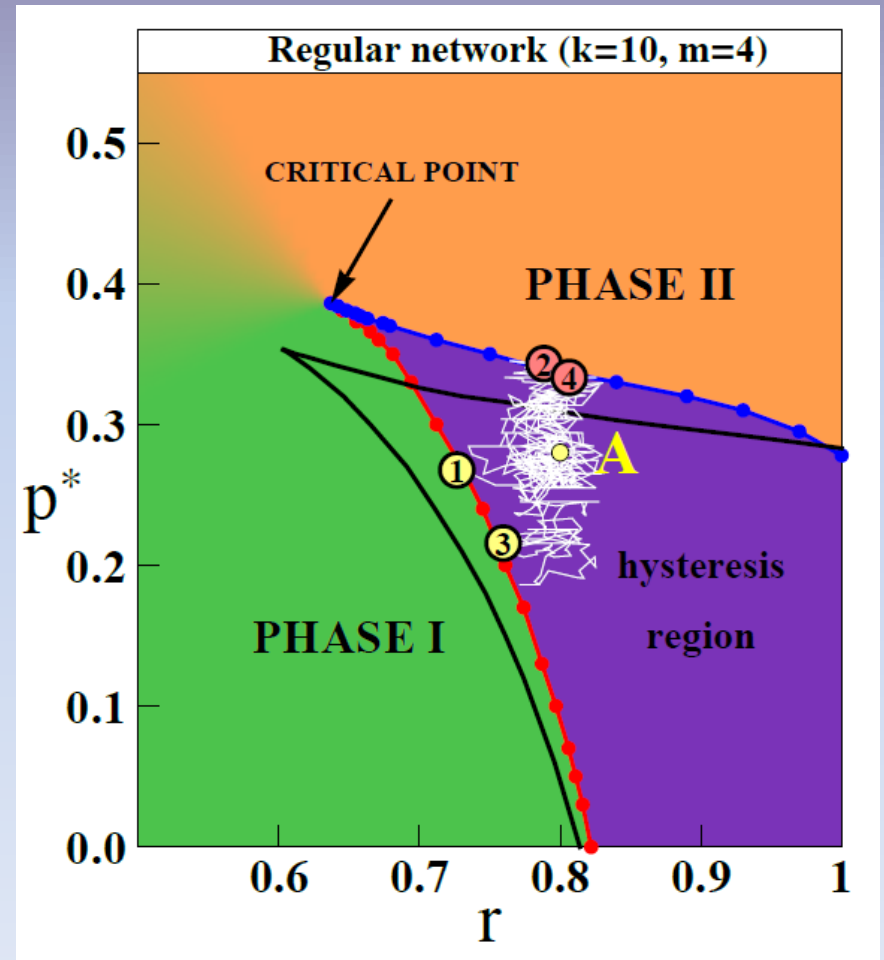
It turns out it can be predicted.

Trajectory $(r_\lambda(t), p_\lambda^*(t))$ in the phase diagram (white line, see below).

The trajectory crosses the spinodals (critical lines) interchangeably, and causes the phase flipping.

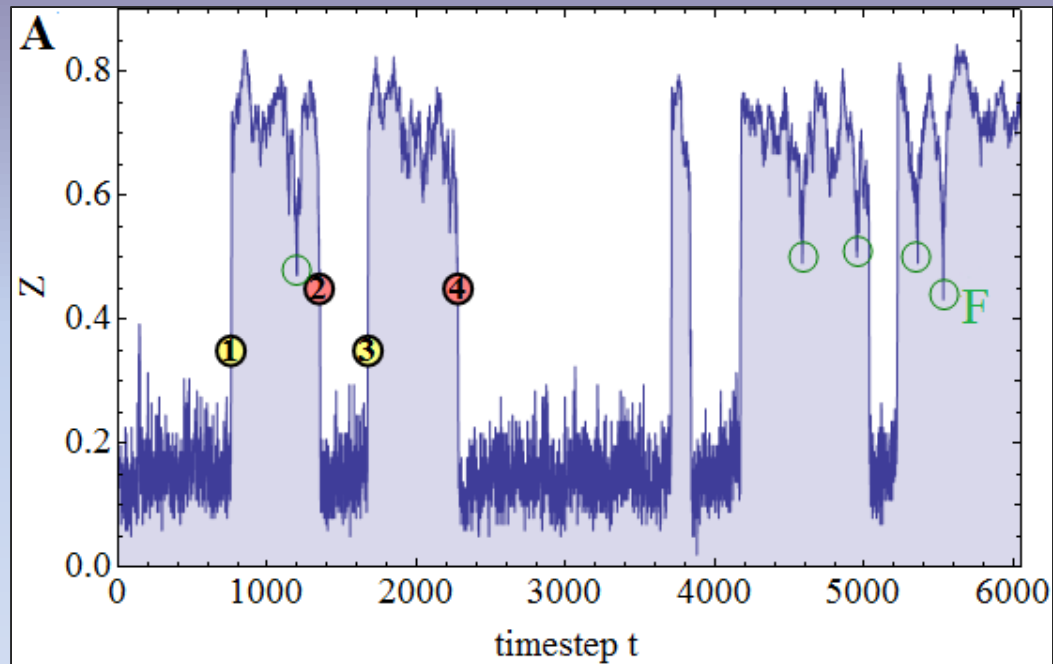


(Observing the network on the micro-level: counting internal and external failures)



Second finite size phenomenon: Flash crashes

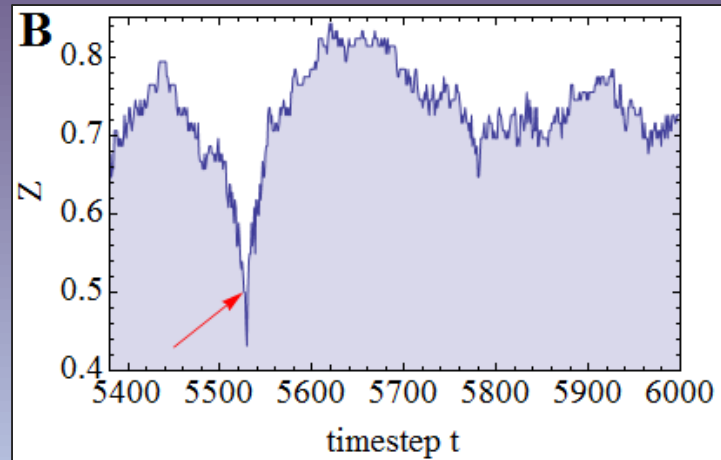
An interesting (and unexpected) by-product of the model:



Sometimes the network rapidly crashes, and then quickly recovers (green circles).

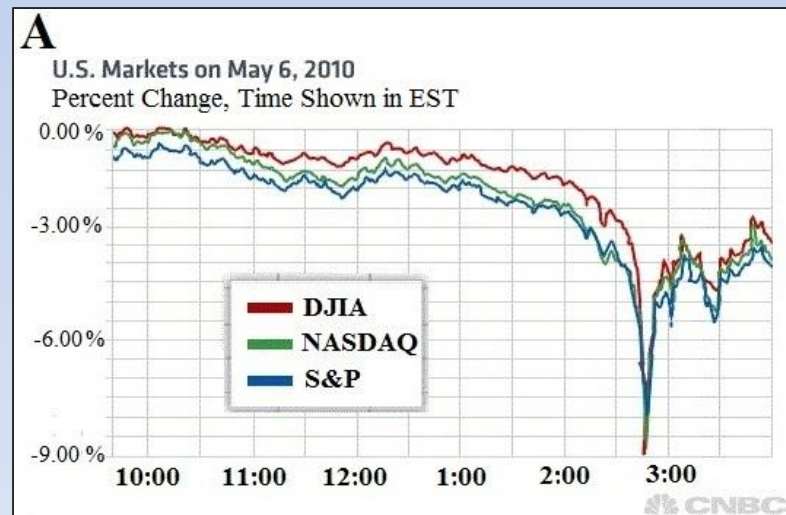
Model predicts the existence of “flash crashes”.

Explanation: Unsuccessful transitions to a lower state.



Real stock markets also show a similar phenomenon.

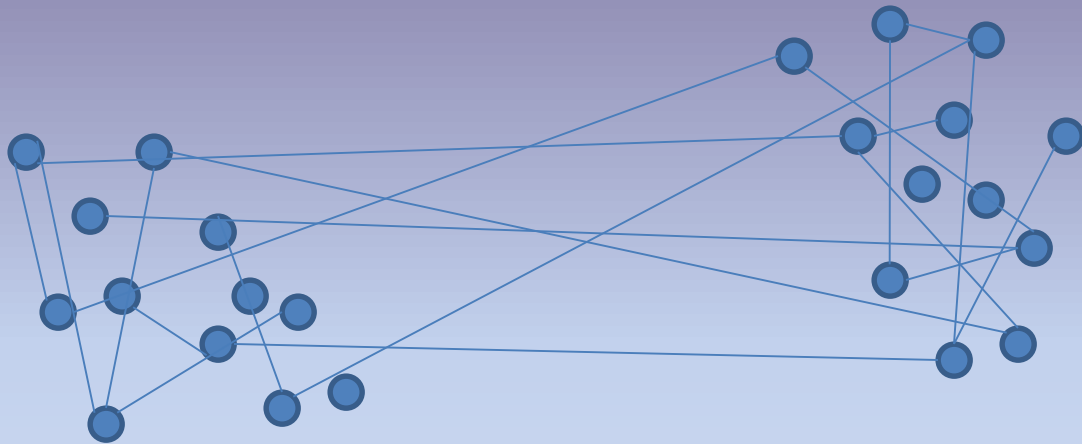
Q: Possible relation?



“Flash Crash 2010”



2.1. Interacting networks

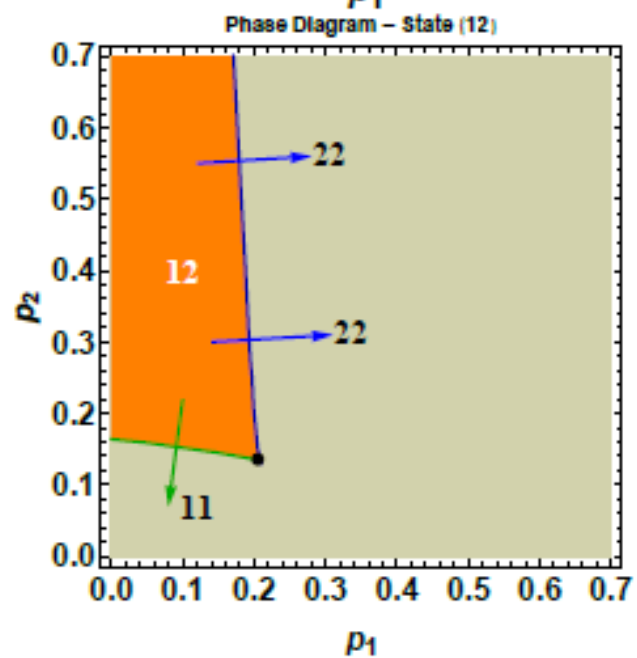
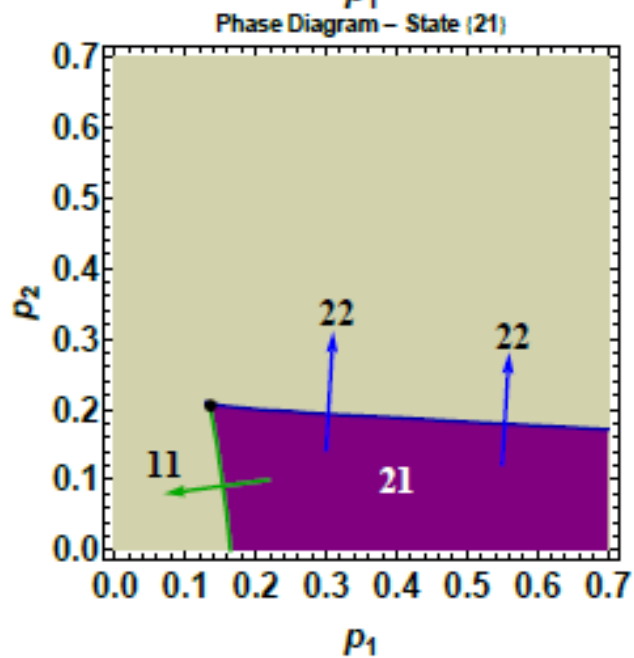
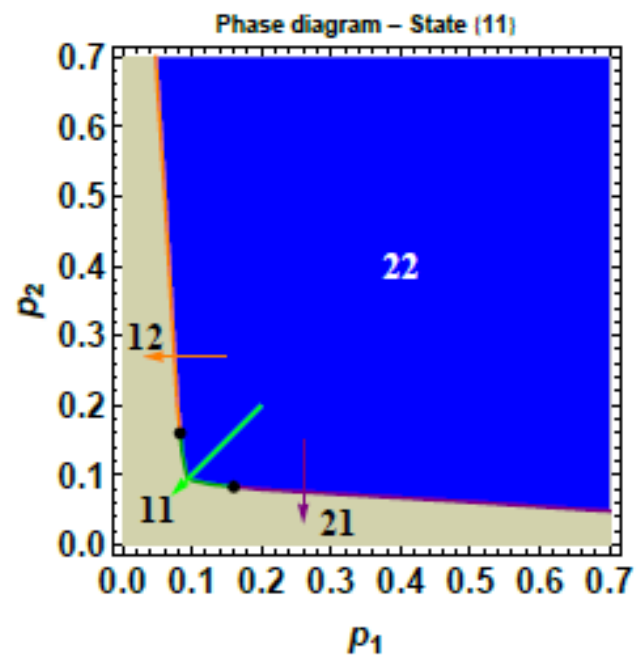
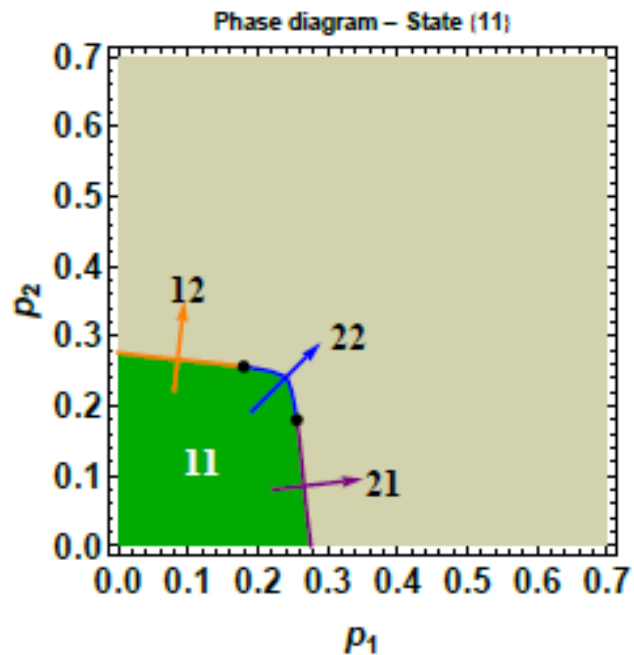


Network A

Network B

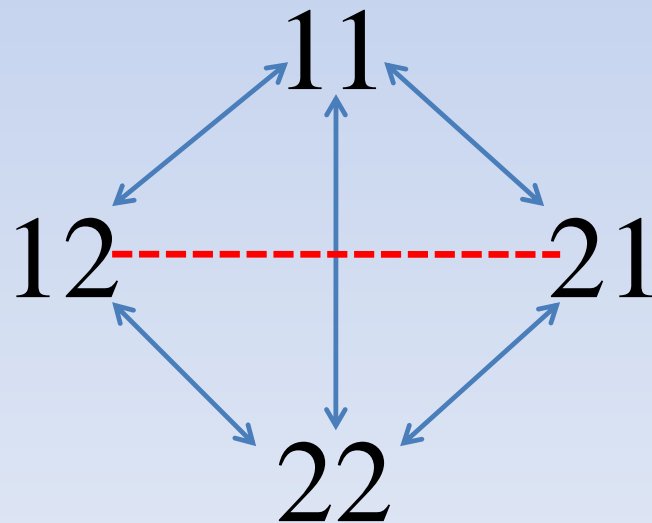
MODEL

FAILURE TYPE	RULE	RECOVERY
Internal failure	With rate p on each node	After time τ
External failure	IF($\leq m$ active neighbors) THEN Extra failure rate r	After time τ'
Dependency failure	IF(companion node from the opposite network failed) THEN Extra failure rate r_d	After time τ''

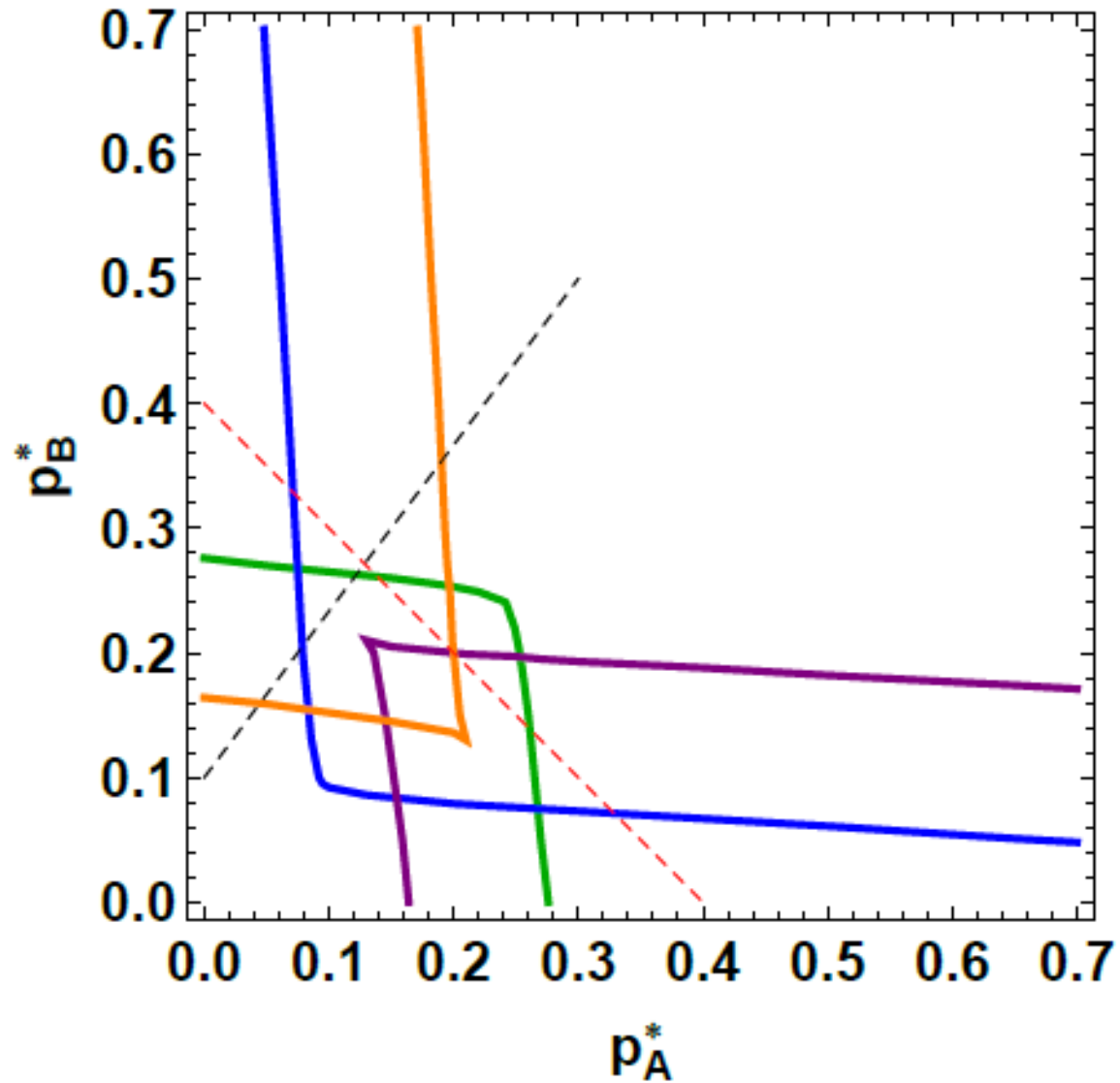


Elements of the phase diagram

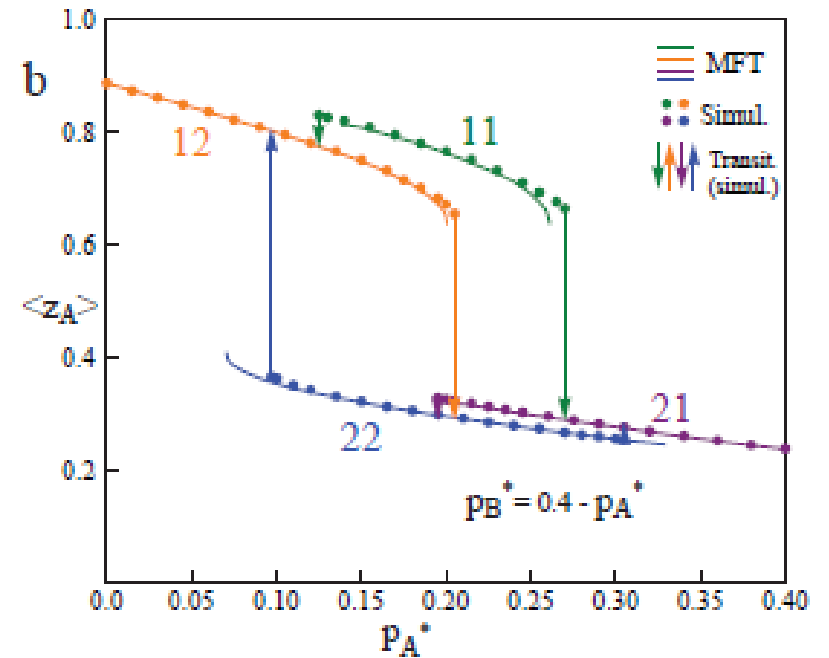
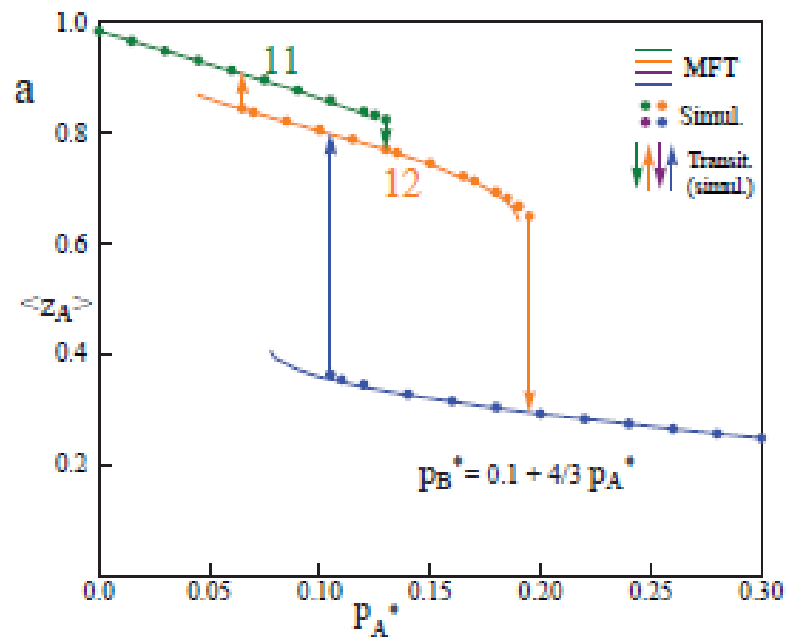
- 2 critical points
- 4 triple points
- 10 allowed transitions
- 2 forbidden transitions



TOTAL PHASE DIAGRAM



HYSTERESIS LOOPS



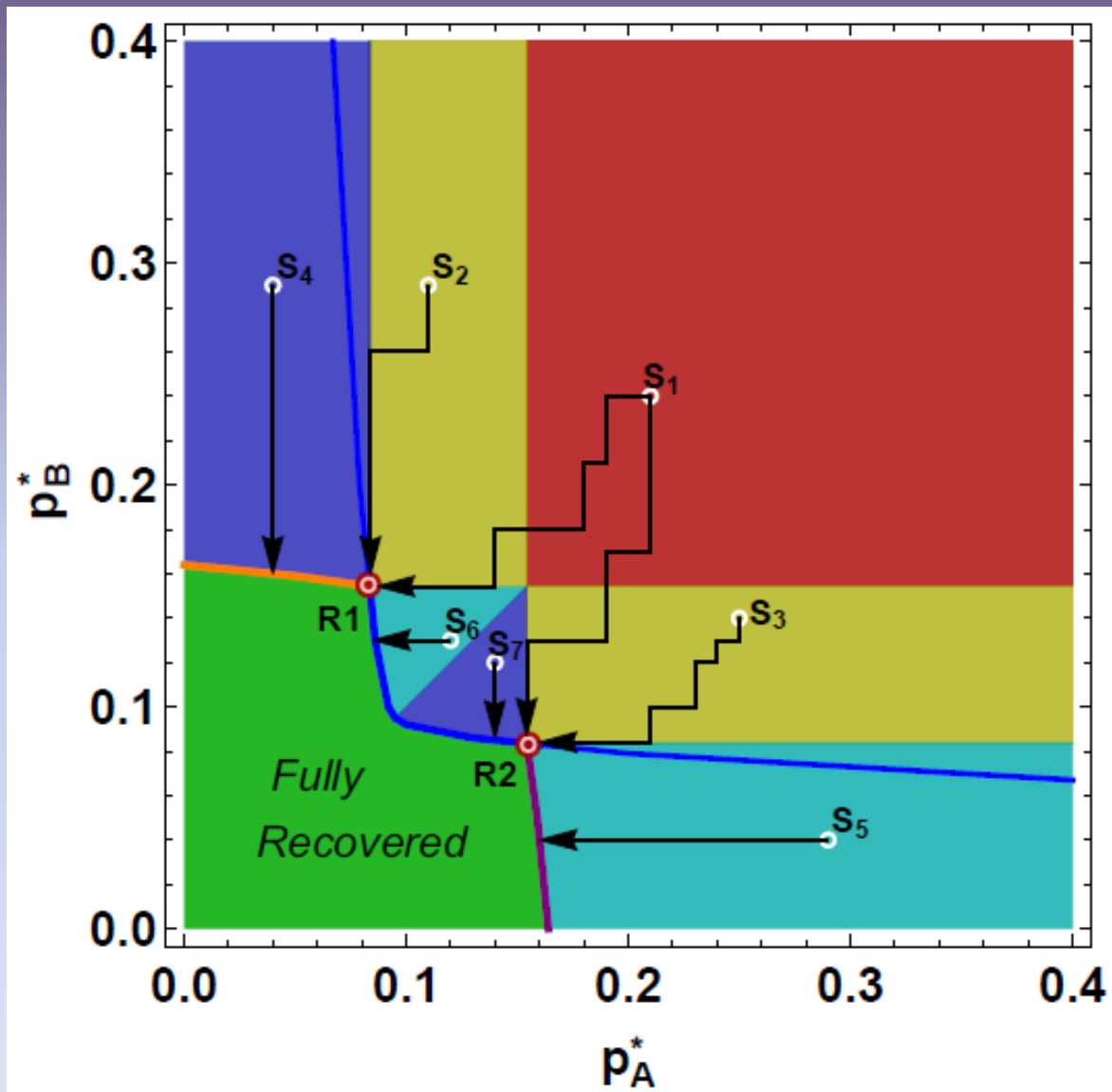
2.2 Problem of optimal repairing

PROBLEM

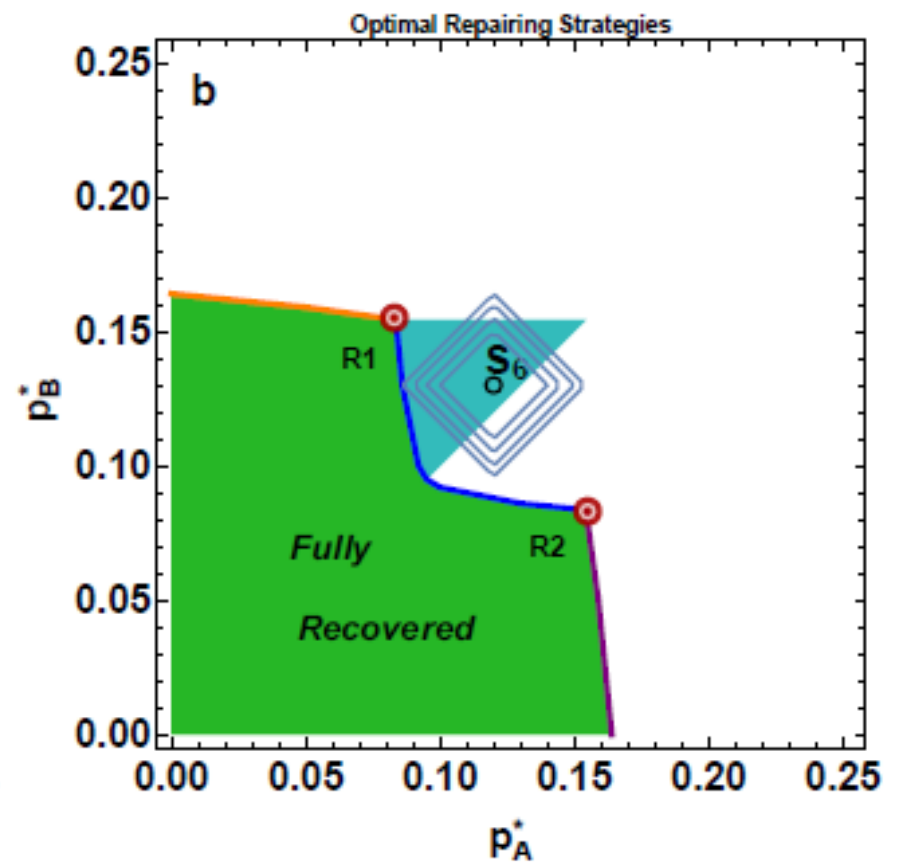
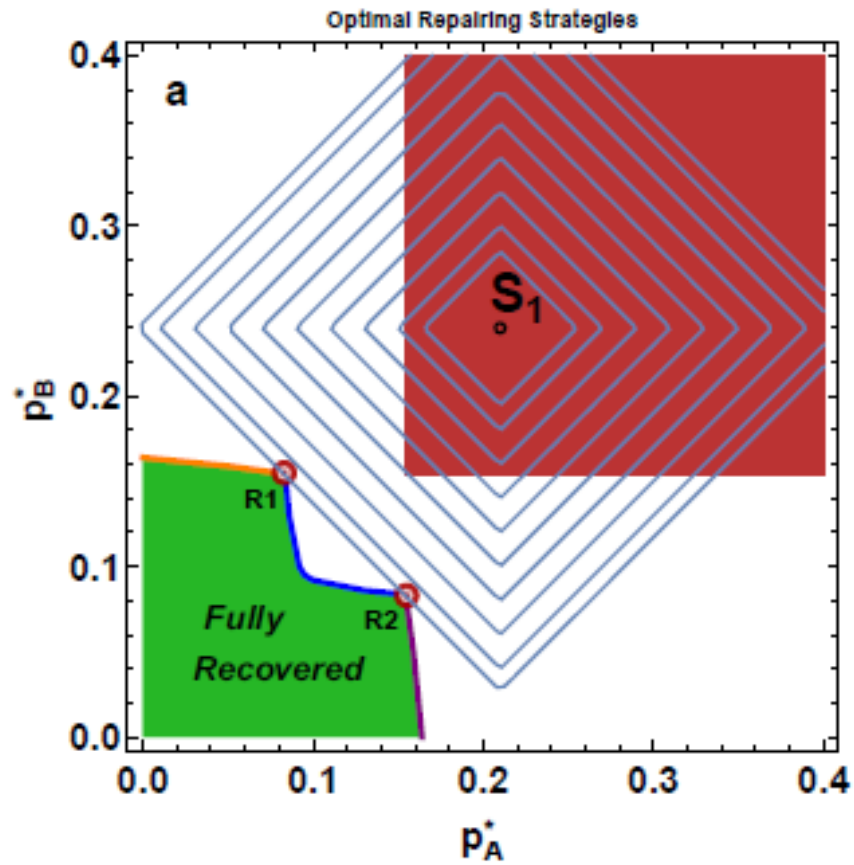
- Consider two interacting networks, both damaged (low activity).
- What is the most efficient strategy to repair such a system?
- We want **minimal intervention** (intervention might be expensive or invasive)
- Scenario common in medicine

Question: What is the **minimum number of repairs** to bring the system to the fully functional state, and **how do we allocate them** (repairs) between the two networks?

SOLUTION:

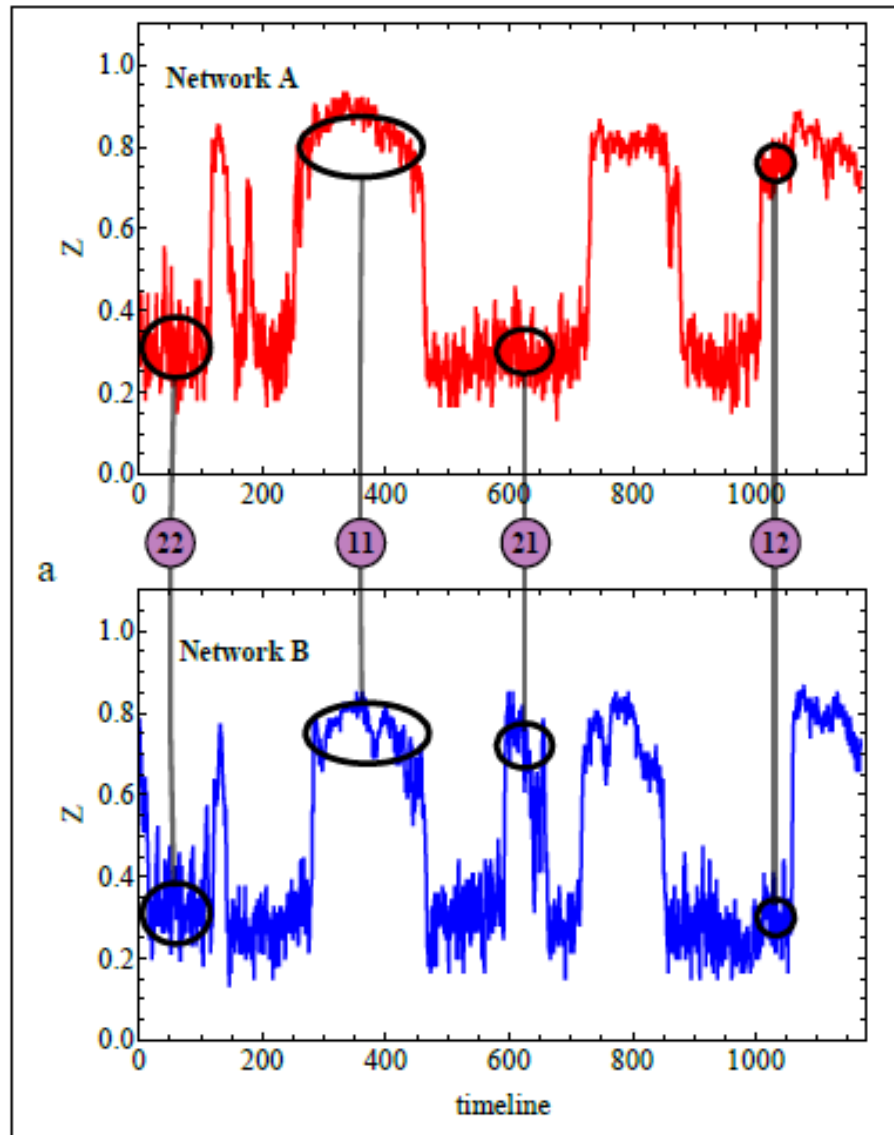


Explanation:



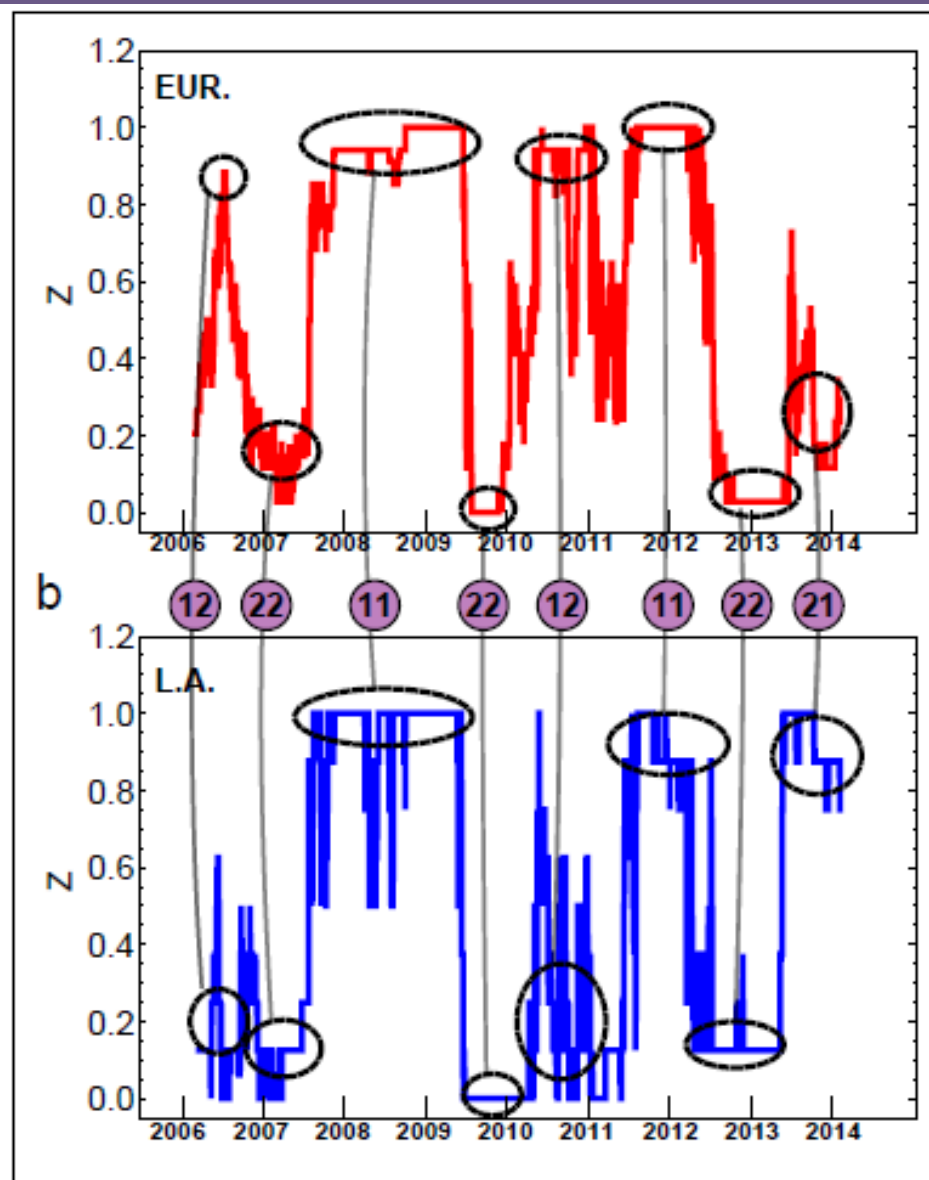
2.3 Dynamics of interacting networks

Activity z
(simulation)



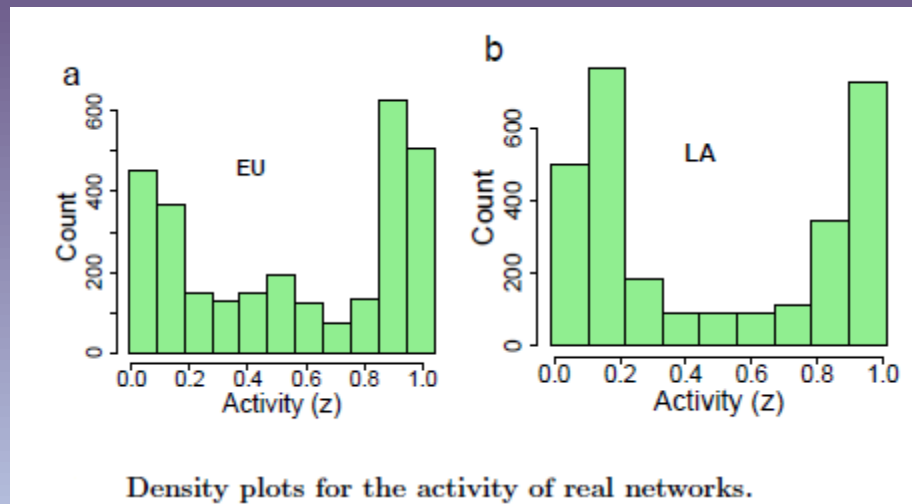
Collective dynamics in simulated interacting networks.

Activity z
(real coupled
networks)

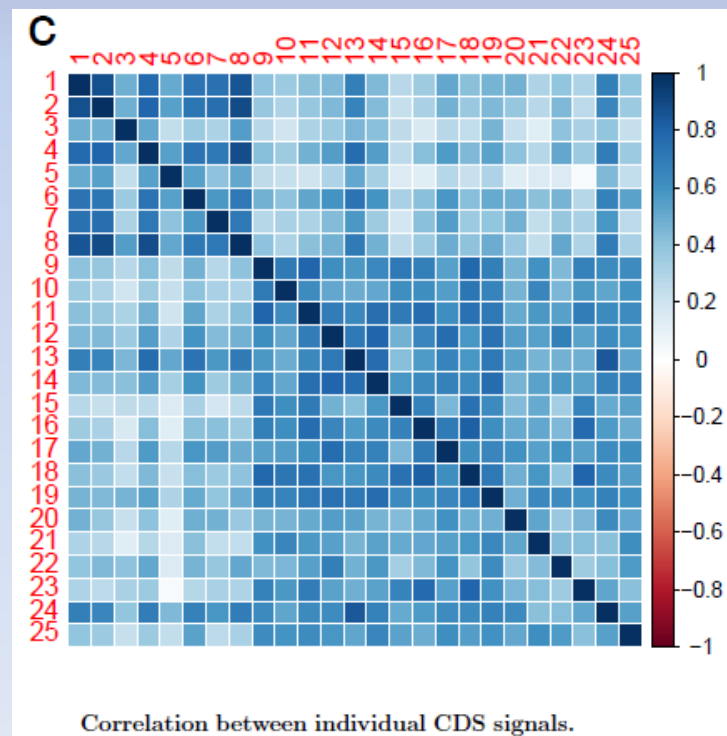


Collective dynamics in real interacting networks.

Density plots

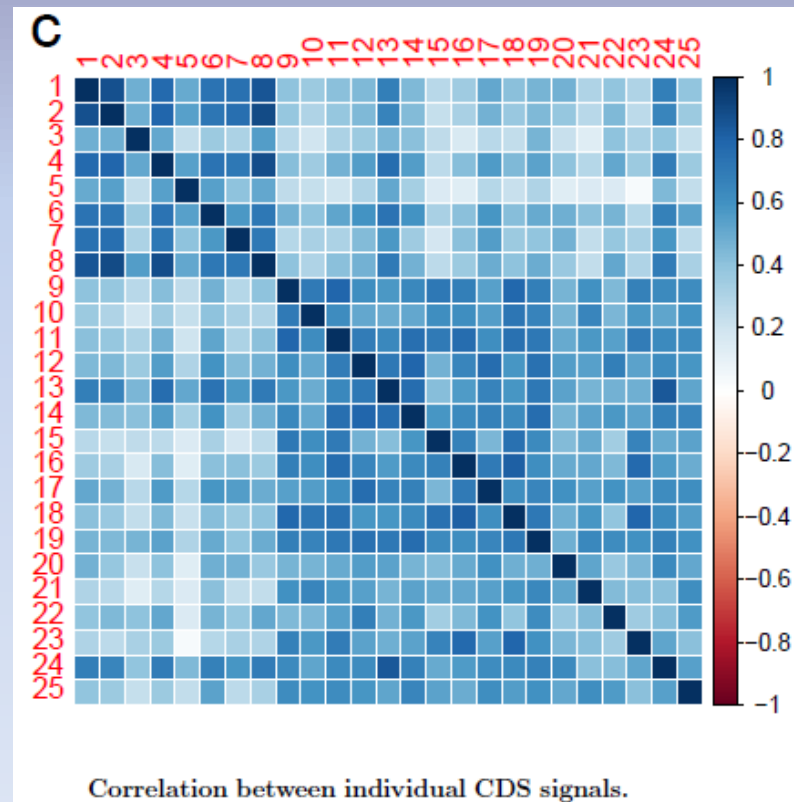


Corr. matrix

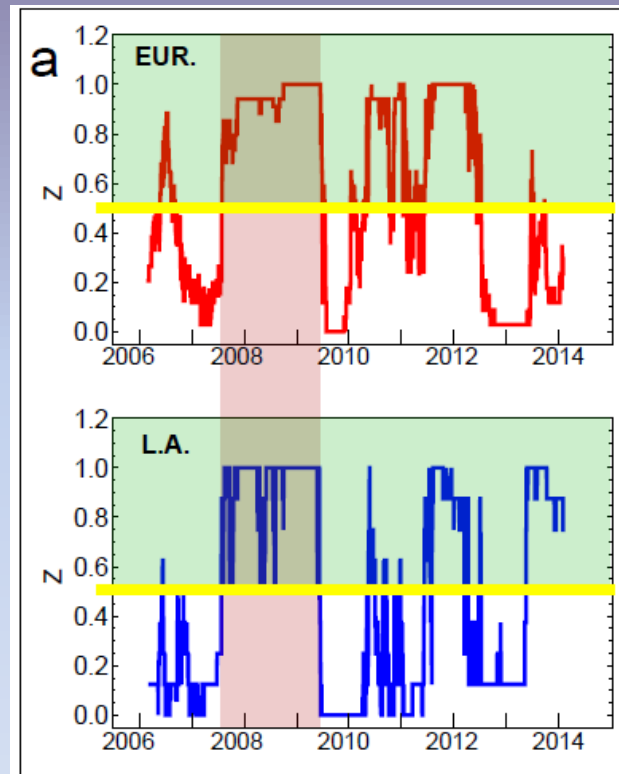


Measuring and estimating model parameters

Building the network



Estimating internal failure parameters (p^*_{EU} and p^*_{LA}):
observing high activity states



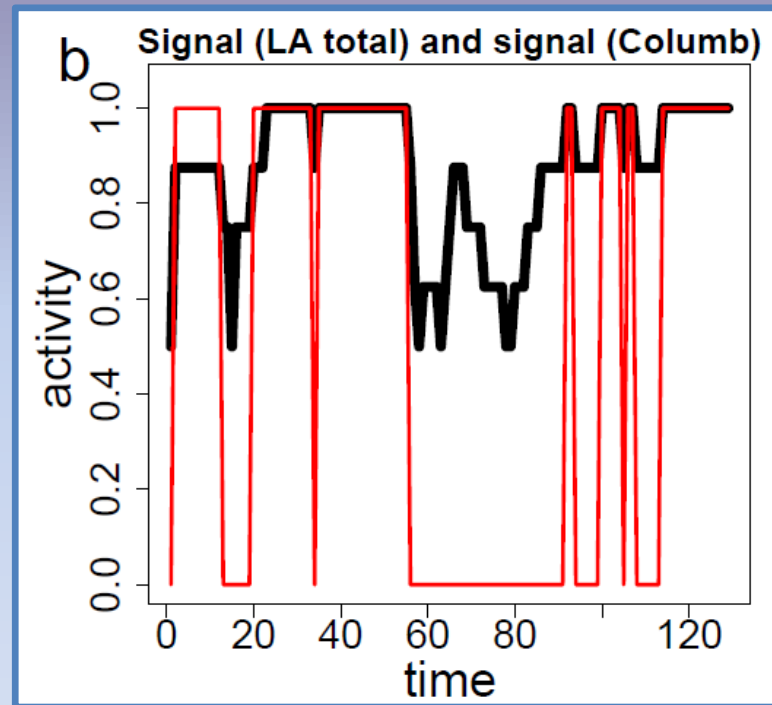
Estimate:

$$p^*_{\text{EU}} = 0.07 \pm 0.01 \quad \text{and} \quad p^*_{\text{LA}} = 0.11 \pm 0.02$$

Alternative method for measuring internal failure and recovery rates:
observing micro dynamics (dynamics of individual nodes)

time of recovery, τ_{EU} and τ_{LA}

crude failure rates p_{EU} and p_{LA}



$$\tau_{\text{EU}} = 13 \pm 2, p_{\text{EU}} = (3.0 \pm 0.5) * 10^{-3}$$

$$p_{\text{EU}}^* = 0.07 \pm 0.01 \text{ (same as before)}$$

$$\tau_{\text{LA}} = 9 \pm 1, p_{\text{LA}} = (7.6 \pm 0.8) * 10^{-3}$$

$$p_{\text{LA}}^* = 0.11 \pm 0.02 \text{ (same as before)}$$

Estimating the external parameters r_{EU} and r_{LA} : **observing low activity states**

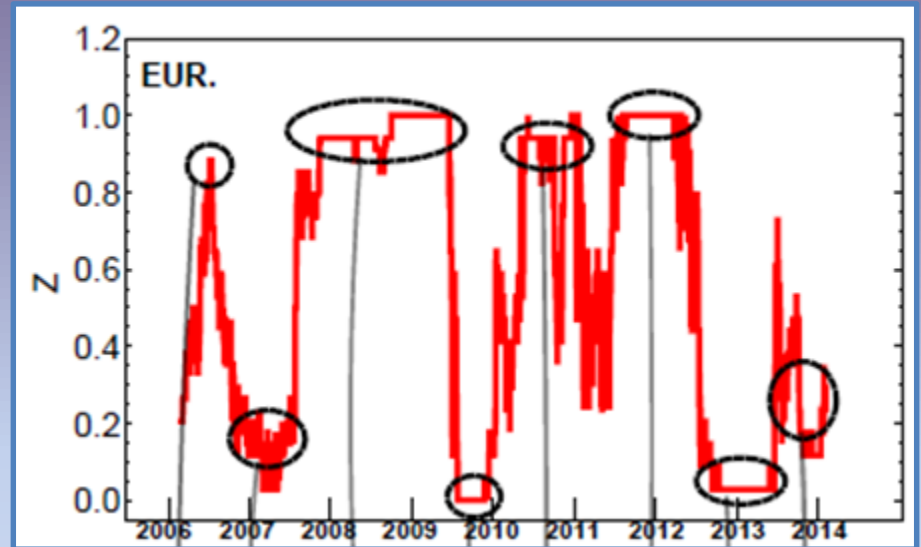
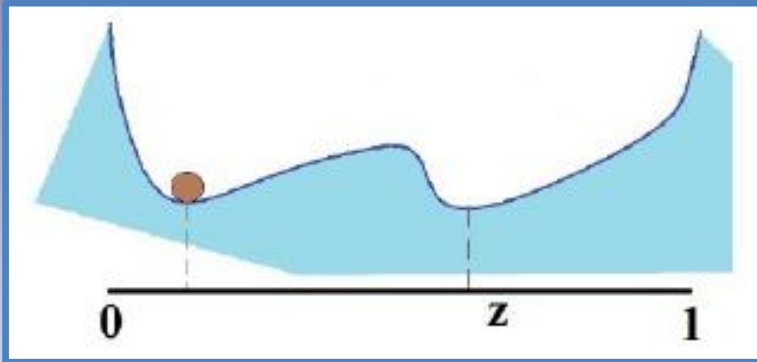
- Contribution from internal failures known
- Contribution from interdependent failures temporary neglected, we introduce a small correction later
- Small influence of thresholds m_{EU} and m_{LA} on the average value of activities z_{EU} and z_{LA}

By measuring $\langle z_i \rangle$ in the low states ($z_{\text{EU}} < 1/2$ & $z_{\text{LA}} < 1/2$) and

already knowing p_i^* , we obtain estimates $r_{\text{EU}} = 0.81 \pm 0.03$ and $r_{\text{LA}} = 0.88 \pm 0.03$.

Estimating the thresholds m_{EU} and m_{LA} : visiting times

double well,



parameter m_{frac}

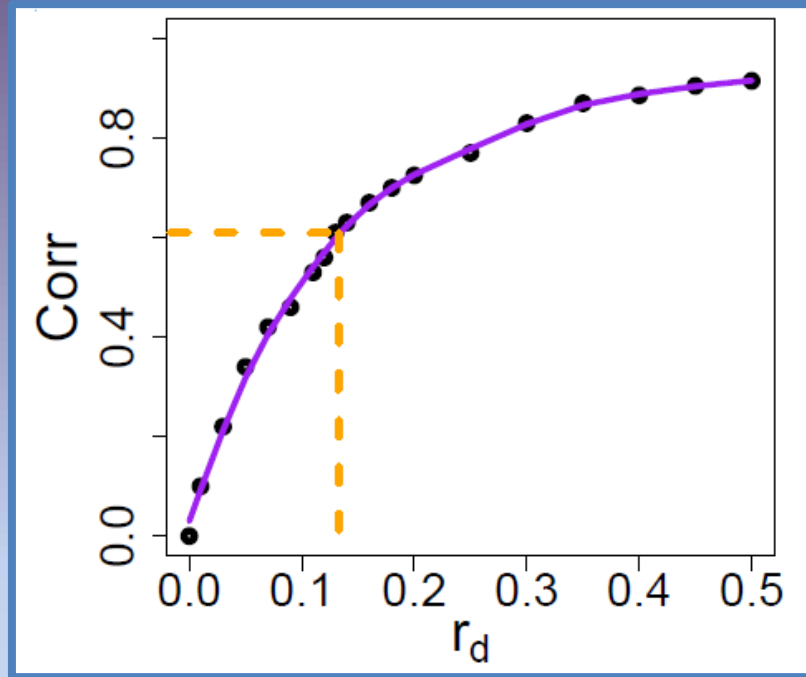
shape of the potential barrier between the wells.

simulating decoupled ($r_d = 0$) EU and LA networks

previously measured parameters (p_{EU}^* , p_{LA}^* , τ_{EU} , τ_{LA} , r_{EU} , r_{LA})

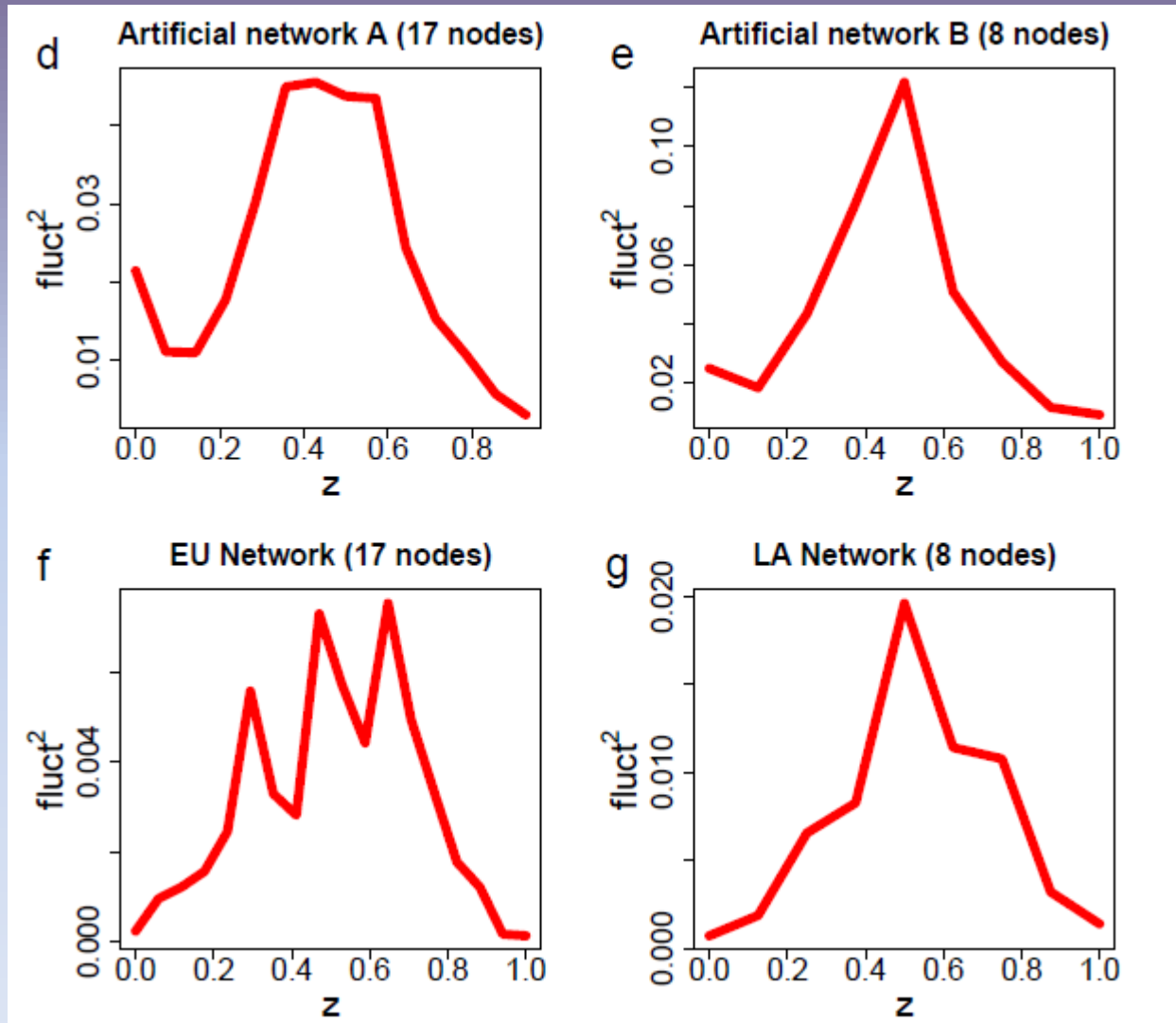
$m_{\text{frac,EU}} = 0.57 \pm 0.02$ and $m_{\text{frac,LA}} = 0.50 \pm 0.02$ for $\langle k \rangle = 3$, to $m_{\text{frac,EU}} = 0.59 \pm 0.02$
and $m_{\text{frac,LA}} = 0.50 \pm 0.02$ for $\langle k \rangle = 7$ ($\langle k \rangle$)

Estimating r_d : correlation between networks EU and LA



$\langle k \rangle$	$m_{frac,EU}$	$m_{frac,LA}$	τ_{EU}	τ_{LA}	r_d
3	0.55	0.43-0.49	0.78	0.87	0.16
4	0.55	0.43-0.49	0.79	0.87	0.14
5	0.57	0.43-0.49	0.79	0.87	0.13
6	0.57	0.43-0.49	0.79	0.87	0.11
7	0.57	0.43-0.49	0.79	0.87	0.10

Similarity in fluctuation size structure



- Thank you for your time.