

# Reply to “Comment on ‘Tests of scaling and universality of the distributions of trade size and share volume: Evidence from three distinct markets’ ”

Vasiliki Plerou and H. Eugene Stanley

Department of Physics and Center for Polymer Studies, Boston University, Boston, Massachusetts 02215, USA

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Analyzing trade-by-trade data for three distinct markets, we showed that the cumulative distributions of trade size display power-law tails  $P\{q > x\} \sim x^{-\zeta_q}$ , with exponents  $\zeta_q$  in the “Lévy stable domain” ( $\zeta_q < \zeta_q^* = 2$ ). Moreover we reported that the exponent values are consistent for all stocks irrespective of stock-specific variables such as market capitalization, industry sector, or the specific market where the stock is traded. Our conclusions were based on using two distinct estimation methods. Rácz *et al.* now propose that one of the estimators we used has slow convergence for a pure power law, particularly as tail exponents approach the boundary  $\zeta_q^* = 2$ . We examine the robustness of our results to specific estimation method by additional analysis using five distinct techniques to estimate  $\zeta_q$ . We find results that are fully consistent with those we had reported, providing compelling evidence that our conclusions hold regardless of estimation procedure.

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## I. INTRODUCTION

We recently analyzed tick-by-tick data for three distinct markets: (i) the New York Stock Exchange (NYSE), (ii) the London Stock Exchange (LSE), and (iii) the Paris Bourse, and reported that the cumulative distribution of individual trade size  $q$  displays a power-law tail

$$P\{q > x\} \sim x^{-\zeta_q}. \quad (1)$$

Here  $\zeta_q$  is the tail exponent [1,2]. In addition to evidence from performing power law regressions and obtaining estimates of  $\zeta_q$ , our analysis provided the following estimates for  $\zeta_q$ :

(a) U.S. stocks: for the largest 1000 U.S. stocks, during the 2 yr period of 1994–1995, we reported using three different methods [1,2]:

$$\zeta_q = \begin{cases} 1.53 \pm 0.07 & \text{(Hill estimator [3])} \\ 1.45 \pm 0.03 & \text{(Scaling of moments)} \\ 1.63 \pm 0.03 & \text{(MS estimator [4]).} \end{cases} \quad (2)$$

(b) LSE stocks: for the largest 85 stocks traded on the LSE that are part of the FTSE<sup>1</sup> 100 index during the 2 yr period of 2001–2002, we found [1]:

$$\zeta_q = \begin{cases} 1.57 \pm 0.01 & \text{[Hill estimator]} \\ 1.58 \pm 0.01 & \text{[MS estimator].} \end{cases} \quad (3)$$

(c) Paris Bourse stocks: for the 13 large stocks that formed part of the CAC 40 index<sup>2</sup> during the 4 yr period of 1995–1999, we found [1]:

$$\zeta_q = 1.53 \pm 0.04 \text{ [Hill estimator]}. \quad (4)$$

Note that all our estimates of  $\zeta_q$  are within the Lévy stable domain  $\zeta_q < \zeta_q^* = 2$ . Moreover, the values of  $\zeta_q$  are consistent not only between stocks within the same market but also across the three markets analyzed [1] (cf. the discussion in

Refs. [5,6] for a discussion of  $\zeta_q$  for LSE stocks).

Reference [7] points out that one of the estimators that we use, the Meerschaert-Scheffler (MS) estimator [4], is constructed specifically for the domain  $\zeta_q < 2$ , and is therefore unable to distinguish between the two cases: (i)  $\zeta_q < 2$  and (ii)  $\zeta_q > 2$ . Our usage of the MS estimator is guided by the range of exponent values  $\zeta_q \approx 1.45 - 1.6$  (obtained from alternate methods listed above), which are within the domain of applicability of the MS estimator. In addition, Ref. [7] shows that, for a “pure” power-law distribution, the MS estimator has slow convergence, and underestimates the tail exponents.

In this Comment, we report the following results:

(i) We first apply five additional estimation techniques to measure the exponent  $\zeta_q$ . Each one of these techniques gives results that are consistent with the values of  $\zeta_q$  [Eqs. (2)–(4)] as reported in Ref. [1]. Together they give compelling evidence in support of the robustness of our conclusion that  $\zeta_q < \zeta_q^* = 2$ .

(ii) Next we discuss the problem of estimating  $\zeta_Q$ , the tail exponent describing the cumulative distribution function,

$$P\{Q > x\} \sim x^{-\zeta_Q}, \quad (5)$$

of share volume in a time interval  $\Delta t$

$$Q_{\Delta t} \equiv \sum_{i=1}^{N_{\Delta t}} q_i, \quad (6)$$

where  $N_{\Delta t}$  denotes the number of trades in the time interval  $\Delta t$ . We show that, for a control generated using  $q_i$  distributed as a power law with  $\zeta_q$  within the Lévy stable domain, aggregation can give apparent exponent values  $\zeta_Q > 2$  similar to those observed in Ref. [8].

(iii) Lastly, we discuss the performance of the MS estimator. Although for a pure power-law distribution [e.g.,  $P(q > x) = a^{\zeta_q} x^{-\zeta_q}$  if  $x > a$ , and 1 otherwise], the MS estimator converges slowly as illustrated in Fig. 1 of Ref. [7]; we note that its convergence and accuracy is better for genuinely Lévy stable distributions.

<sup>1</sup>See weblink [www.ftse.com](http://www.ftse.com)

<sup>2</sup>See weblinks [www.nyse.com/cac40](http://www.nyse.com/cac40) and [http://en.wikipedia.org/wiki/CAC\\_40](http://en.wikipedia.org/wiki/CAC_40)

**II. ESTIMATION OF THE EXPONENT  $\zeta_q$  FROM FIVE ADDITIONAL ESTIMATION TECHNIQUES**

To obtain additional confirmation that  $\zeta_q$  is robust to the choice of estimation technique, we have further analyzed the data for the 116 most actively traded U.S. stocks using five separate estimation techniques:

**A. Technique 1: max-spectrum estimator**

The *max-spectrum estimator*, proposed in Ref. [9], is a unique approach for estimating the tail exponent  $\zeta_q$ . Consider an *i.i.d.* series  $X_i$  with the cumulative distribution  $P(X > x) \sim x^{-\alpha}$ . The max-spectrum estimator [9] utilizes the relationship that the maximum event observed over a block of size  $m$  scales as  $m^{1/\alpha}$ . We find [10,11]

$$\zeta_q = 1.59 \pm 0.02. \tag{7}$$

**B. Technique 2: moment estimator**

The *moment estimator* [12] is a generalization of Hill’s original method obtained by including a correction term. We obtain [13]

$$\zeta_q = 1.73 \pm 0.04. \tag{8}$$

**C. Technique 3: Fraga-Alves estimator**

The *Fraga-Alves estimator* [14] is a location-invariant estimator based on Hill’s original estimator. Alternative techniques such as Pickand’s estimator [15] have the same location-invariant property although it is found to display large variance. We find [16]

$$\zeta_q = 1.71 \pm 0.03. \tag{9}$$

**D. Technique 4: discrete Hill estimator**

The *discrete Hill estimator* [17] is a variant of Hill’s method for discrete data sets. Applying this estimator to the U.S. data, we find [18]

$$\zeta_q = 1.55 \pm 0.02. \tag{10}$$

**E. Technique 5: Hill estimator with optimal threshold**

The *Hill estimator with optimal threshold* [17] relies on using the Kolmogorov-Smirnov statistic to determine the optimal estimation threshold. The optimal threshold is chosen such that the probability distributions of the data and the best-fit power law are as similar as possible beyond this threshold. We find [19,20]

$$\zeta_q = 1.69 \pm 0.02. \tag{11}$$

Each of these five distinct estimation techniques yields results that confirm our findings reported in Ref. [1]. Together, they provide compelling evidence that  $\zeta_q < 2$ .

We conclude with a graphical analysis of the distribution of trade size  $P(q > x)$ , certainly the most direct method of

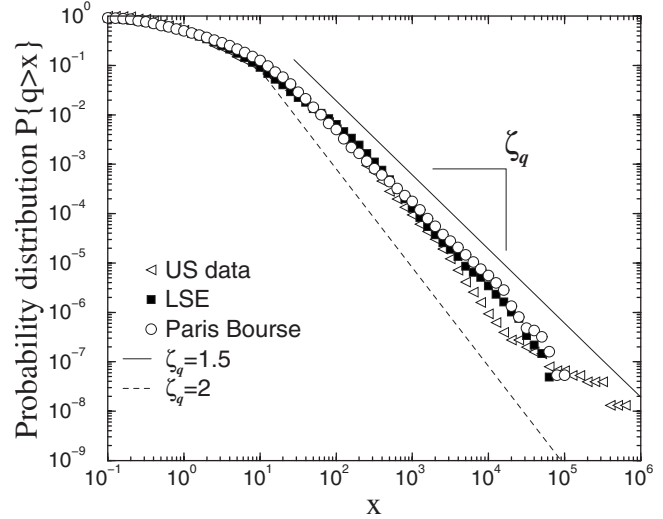


FIG. 1. Distribution function  $P(q > x)$  of the trade size  $q$  for all three databases analyzed in Ref. [1]. The data for each stock have been scaled by its median. The tails for all three distributions seem consistent with  $\zeta_q < 2$  within the Lévy stable domain. Power-law regressions give  $\zeta_q = 1.55 \pm 0.04$  (NYSE),  $1.73 \pm 0.02$  (LSE), and  $1.60 \pm 0.03$  (Paris Bourse). Please refer to the text for more accurate exponent estimates.

analyzing the tail behavior (Fig. 1). The solid line corresponds to  $\zeta_q = 1.5$  while the dashed line shows the limit  $\zeta_q = 2$ . We note that (a) the three distributions are mutually compatible, as corroborated by various exponent estimates listed above, and (b) all three display tail exponents which are consistent with  $\zeta_q < 2$ .

**III. ESTIMATION OF THE EXPONENT  $\zeta_Q$**

Next we focus on share volume  $Q_{\Delta t}$  defined in Eq. (6). Consistent estimation of the exponent  $\zeta_Q$ , which describes the tail behavior of the cumulative distribution of share volume  $P(Q > x)$ , is a more challenging problem than estimating  $\zeta_q$ . First,  $Q_{\Delta t}$  acquires long-range correlations from  $N_{\Delta t}$  [2], so unlike trade size  $q$ , it has pronounced dependencies. Second, estimators such as the Hill estimator which rely on an estimation threshold give biased results (cf. Fig. 6 in Ref. [1]) for aggregated data such as  $Q_{\Delta t}$ . This estimation bias, which increases with the degree of aggregation (i.e., with increasing  $\Delta t$ ), apparently led Ref. [8] to conclude that the “true” exponent  $\zeta_Q$  increases with increasing  $\Delta t$  with an exponent estimate  $\zeta_Q > 2$  implying finite variance. Similar bias is present for other estimators which rely on an estimation threshold, including the “shifted Hill” method, also applied in Ref. [8].

It is instructive to compare the performance of various estimators when applied to computer-generated aggregated data such as

$$Y_{\Delta t} \equiv \sum_{i=1}^N x_i, \tag{12}$$

where  $x_i$  is generated to follow a power-law distribution with exponent  $\zeta_x$  [cf. Eq. (16) of Ref. [1]], and  $N$  is generated to

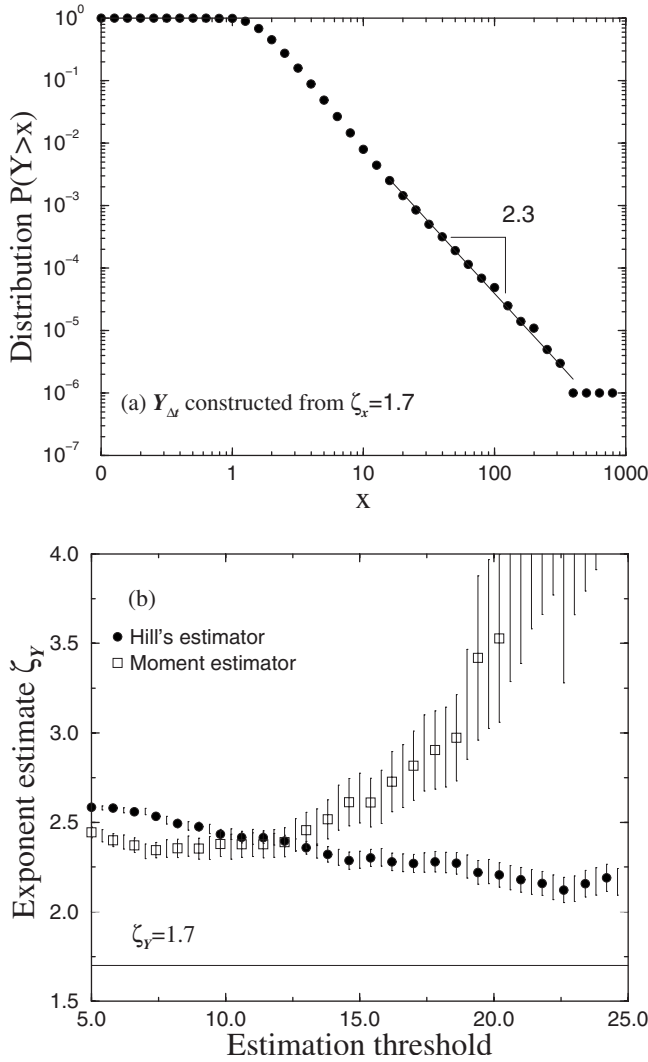


FIG. 2. (a) Distribution function  $P(Y > x)$  of aggregated time series  $Y_{\Delta t} \equiv \sum_{i=1}^{N_{\Delta t}} x_i$ , where  $x_i$  are generated to have a pure power-law tail of  $\zeta_x = 1.7$ ,  $N_{\Delta t}$  is generated to have a pure power-law tail of  $\zeta_{N_{\Delta t}} = 3$ , and  $\langle N_{\Delta t} \rangle$  is set to have the same average value as  $\langle N_{\Delta t} \rangle$  for  $\Delta t = 15$  min in the NYSE data. The solid line shows a power-law fit which gives the estimate  $\hat{\zeta}_Y = 2.28 \pm 0.05$ , significantly larger than the true value of  $\zeta_Y = 1.7$ . (b) Hill estimator and the moment estimator [12] applied to  $Y$  as a function of estimation threshold shows an exponent estimate  $\hat{\zeta}_Y > 2$  although the true value is  $\zeta_Y = \zeta_x = 1.7$ .

have a power law  $\zeta_N = 3$  (similar to empirical results [21]). Consider the case when  $\zeta_x = 1.7$  (similar to some of the estimates we obtain for  $\zeta_q$ ). Since  $\zeta_x$  is within the Lévy stable domain, we expect the asymptotic behavior  $P(Y > x) \sim x^{-\zeta_Y}$  with  $\zeta_Y = \zeta_x = 1.7$  (since  $\zeta_x < \zeta_N$ ) [22]. However, as shown in Fig. 2(a), the distribution function  $P(Y > x)$  is virtually indistinguishable from a power law with a larger exponent value—regressions give  $\zeta_Y = 2.29 \pm 0.04$ .

Figure 2(b) shows the results of applying the Hill’s estimator and the moment estimator [12] to the same data. Clearly both of these estimators provide exponent estimates significantly larger than the true value of  $\zeta_Y = 1.7$ . Note that these estimates, including the power law regression estimate  $\zeta_Y = 2.29 \pm 0.04$  are not unlike the estimates of  $\zeta_Q \approx 2.3$  re-

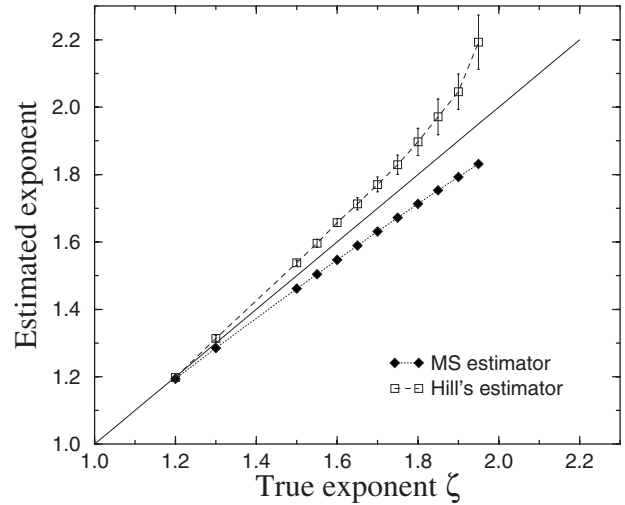


FIG. 3. Comparison of the exponent estimates  $\hat{\zeta}$  obtained from the MS and the Hill’s estimator for symmetric Lévy stable distributed data generated using the procedure of Ref. [24].

ported in Ref. [8]. Indeed, for truly Lévy stable distributions, it is well documented that common estimation techniques such as Hill’s estimator give exponent estimates which have significant upward bias when the tail exponent is in the range  $1.5 < \zeta_q < 2$  [23]. This fact is particularly relevant in this case since  $\zeta_q < 2$ , so as  $N$  becomes large, the distribution of  $Q$  approaches a Lévy stable distribution as claimed in Ref. [1].

#### IV. RATE OF CONVERGENCE OF THE MS ESTIMATOR

Reference [7] notes that the MS estimator has slow convergence. We have explored the possibility of using other threshold-independent techniques for estimating  $\zeta_Q$ , e.g., the Hosking-Wallis (HW) estimator [25]. Although the HW estimator does not have the limitation that its domain of applicability is for exponents  $< 2$ , it is reliable only for pure Pareto distributions [25] and gives unstable results in the presence of any departures from the pure Pareto form, even at small values. For example, the HW estimator would provide reliable results for control data such as presented in Ref. [7]. In contrast, the MS estimator is more robust to this effect although the rate of convergence is slow. As shown in Fig. 1 of Ref. [7], the deviation between the actual and estimated exponent values is particularly large for the pure power-law form as  $\zeta_q$  approaches 2 even with  $5 \times 10^5$  points.

For Lévy stable distributed data however, this deviation is more benign. To illustrate the performance of the MS estimator, we have generated surrogate data following a stable Lévy distribution using the methods of Ref. [24]. Figure 3 shows that the MS estimator underestimates the true exponent while Hill’s estimator overestimates. As per the discussion in Sec. III of Ref. [4], the performance of the MS estimator is superior to that illustrated in Ref. [7] because the data in Fig. 3 is generated to follow a Lévy stable law in contrast to a distribution with a power-law tail as in Ref. [7]. We note that, since  $\zeta_q < 2$ , the distribution of the aggregated

data  $Q$  would more closely resemble the Lévy stable data in Fig. 3 so the MS estimator, although its convergence is slow, is useful to estimate  $\zeta_Q$ . In addition, our numerical tests show that the MS estimator is useful in detecting dependencies of the exponent on other variables (more so than Hill's technique), which is particularly relevant in the context of testing the dependence of  $\zeta_Q$  on variables such as market capitalization.

In summary, we applied five additional estimation techniques to calculate the exponent  $\zeta_q$ . We first show that each of these techniques give results that are consistent with the values of  $\zeta_q$  reported in Ref. [1]. Together they give compelling

evidence in support of the robustness of our conclusion that  $\zeta_q < 2$ . Second, we discussed the problem of estimating  $\zeta_Q$ , the tail exponent describing the decay of the cumulative distribution of share volume  $Q_{\Delta}$ . Third, we showed that, for surrogate data generated assuming  $q_i$  is distributed as a power law within the Lévy stable domain  $\zeta_q < 2$ , aggregation can give apparent exponent values  $\zeta_Q > 2$ .

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 [11] The error bars listed throughout this paper correspond to one-standard deviation scaled by the square root of the number of observations. Note that this is accurate only for independent data, and tends to underestimate the true magnitude of the error bars. Applying a bootstrap procedure can provide a more reliable estimate of the error bars which indicate values that are  $\approx 4$ – $5$  times larger.  
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