Which Artificial Intelligence Algorithm Better Predicts the Chinese Stock Market?

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ABSTRACT Unpredictable stock market factors make it difficult to predict stock index futures. Although efforts to develop an effective prediction method have a long history, recent developments in artificial intelligence and the use of artificial neural networks have increased our success in nonlinear approximation. When we study financial markets, we can now extract features from a big data environment without prior predictive information. We here propose to further improve this predictive performance using a combination of a deep-learning-based stock index futures prediction model, an autoencoder, and a restricted Boltzmann machine. We use high-frequency data to examine the predictive performance of deep learning, and we compare three traditional artificial neural networks: 1) the back propagation neural network; 2) the extreme learning machine; and 3) the radial basis function neural network. We use all of the 1-min high-frequency transaction data of the CSI 300 futures contract (IF1704) in our empirical analysis, and we test three groups of different volume samples to validate our observations. We find that the deep learning method of predicting stock index futures outperforms the back propagation, the extreme learning machine, and the radial basis function neural network in its fitting degree and directional predictive accuracy. We also find that increasing the amount of data increases predictive performance. This indicates that deep learning captures the nonlinear features of transaction data and can serve as a powerful stock index futures prediction tool for financial market investors.

INDEX TERMS Prediction methods, artificial neural networks, stock markets, deep learning.

I. INTRODUCTION

Stock market prediction is a classic topic in both financial circles and academia. Extreme stock market fluctuations, e.g., the global stock market turmoil in February 2018, damage financial markets and the global economy. We thus need a more effective way of predicting market fluctuations. Among the many predictive efforts over the last few decades [1]–[3], some have had success using quantitative methods [4]–[9], such as autoregressive integrated moving average (ARIMA) models, artificial neural networks, support vector machine, and neuro-fuzzy based systems, but because of the nonlinear characteristics of stock market behavior, financial economists continue to debate these methodologies [10]–[13].

Recently “deep learning” (DL) has attracted a great deal of attention in many research fields. DL is a new area of machine learning that has improved the ability of computers in areas of image recognition and classification, natural language processing, speech recognition, and social network filtering [14]–[16]. In some cases the results are comparable to or even superior to those of human experts [17], [18]. The structure of DL is a multi-layer neural network that uses a cascade of multiple layers of nonlinear processing units to extract and transform various features. Its learning can be either supervised or unsupervised, and it forms a hierarchy of concepts by utilizing multiple representation levels that correspond to different levels of abstraction [19]. The use of DL has improved computational power and big data processing, and it allows more sophisticated algorithms. Previous studies indicate that DL more efficiently solves nonlinear problems than traditional methods [19]–[21]. Irrespective of the level of complication or the presence of linear and nonlinear big data financial market factors, DL can extract abstract features
and identify hidden relationships in financial markets without making econometric assumptions [22]. Traditional financial economic methods and other quantitative techniques cannot do this. Over against the limitations of existing models DL can process high frequency big data, analyze the financial market, and predict stock returns [23], [24]. When setting the parameters of artificial neural networks, the learning rate, epochs, goals, and number of artificial neurons, all must be taken into account to achieve desirable results [25], [26]. DL can extract abstract features without subjective interferences. We thus do not need to add influencing factors or control variables when we use a large time-series dataset to predict financial market behavior. Some other methods have been applied to time-series analysis [27]–[29]. For example, Gao et al. [28] propose a new wavelet multiresolution complex network for analyzing multivariate time series, which is capable of analyzing the information in the dynamical and topological fields and is successfully applied in many research fields. But DL can provide accurate financial market time-series forecasting, and the accuracy increases as the size of the database increases [30]. Thus DL is perfect for time-series prediction in the financial market.

We here use deep learning to predict stock market behavior, and we compare the performance of this approach with the performance of traditional back propagation (BP) network, extreme learning machines (ELM), radial basis function (RBF). Many studies have used traditional predictive methods and low frequency data to predict stock prices and returns, but the market inefficiencies caused by high frequency microstructure noise may provide additional profit opportunities. When traditional predictive methods are used to examine high frequency data they are also subject to over-fitting and low accuracy.

We thus use a DL-based prediction model and high frequency time-series data from 20 February 2017 to 20 April 2017 in the Chinese stock market to predict stock index futures and compare the predictive performance with that from other methods. In Sec. 2 we describe deep learning and other artificial intelligence algorithms. In Sec. 3 we describe the data source and the data characteristics and propose the criteria for evaluating the performance of our model. Sec. 4 provides our empirical results, and Sec. 5 provides the conclusions.

II. DEEP LEARNING AND OTHER ARTIFICIAL INTELLIGENCE ALGORITHMS

A. DEEP LEARNING

Deep learning is a machine learning technology that bypasses manual extraction and extracts features mechanistically. Deep learning simulates the cerebral cortex and abstract data or signals, layer by layer, and models the image recognition of the cerebral cortex. Deep learning first extracts low-level features from original signals. It then extracts high-level features, first from low-level features and then from higher-level features. In an image recognition system, the original signals are pixels. The low-level features are the edges of objects. The high-level features are the contours, and the highest-level feature is the image. Using the characteristics of high-level classification, deep learning outputs forecast results [15]. Figure 1 shows the deep learning hierarchy.

Deep learning abstracts and transfers features of data through different layers. Here \( f \) is the activation function. Given input \( X \) and predictable output \( \hat{Y} \), the prediction function of deep learning is

\[
M_1 = f_1(W_0X + b_0), \\
M_2 = f_2(W_1M_1 + b_1), \\
\vdots \\
M_L = f_L(W_{L-1}M_{L-1} + b_{L-1}), \\
\hat{Y}(X) = W_LM_L + b_L. 
\]

Here \( W \) indicates the weight matrices, \( b \) the biases, and \( L \) the number of layers. The training process of deep learning has two stages. The first is unsupervised learning from bottom to top. The second is supervised learning from top to bottom. The widely used data representation methods in deep learning are two nonlinear transformations, (i) the autoencoder (AE) and (ii) the restricted Boltzmann machine (RBM).

1) AUTOENCODER

The autoencoder learns a representation (an encoding) for a dataset, typically in order to reduce the dimensionality. It compresses the input into a latent-space representation and then reconstructs the output from this representation (see Fig. 2).

![FIGURE 2. Principle of autoencoder.](image-url)
An autoencoder consists of an encoder and a decoder [14], defined as transitions \( \phi \) and \( \varphi \),
\[
\begin{align*}
\phi : \chi & \rightarrow \kappa \\
\varphi : \kappa & \rightarrow \chi \\
\phi, \varphi & = \text{arg min} \|X - (\varphi \circ \phi)X\|^2. \quad (2)
\end{align*}
\]
In the encoder stage, \( x_l \in \mathbb{R}^d = \chi \) is the input of layer \( l \) mapped to \( y_l \in \mathbb{R}^k = \kappa \) with the function \( y_l = f_l(W_l x_l + b_l) \). A sigmoid function is typically used to activate function \( f \), which we also use here. In the decoder stage, \( y_l \) is mapped to the reproduction of the same shape as \( x_l \) using the function \( x'_l = f'_l(W'_l y_l + b'_l) \). Autoencoders are trained to minimize reconstruction errors,
\[
E(X, X') = \|X - X'\|^2 = \|X - f'(W'(f(WX + b)) + b')\|^2. \quad (3)
\]
We here use autoencoders to set initial weights and thresholds to reduce the error and more rapidly reach the desired range.

2) RESTRICTED BOLTZMANN MACHINE

The restricted Boltzmann machine (RBM) is a generative stochastic artificial neural network that can learn a probability distribution. It is a restricted variant of a Boltzmann machine in which neurons must form a bipartite graph. Depending on the task, the training of an RBM can be either supervised or unsupervised. A standard RBM has a hidden binary-value and visible units. Here \( X, Y \) are the visible (input) and hidden layers, respectively. The energy of a configuration (a pair of boolean vectors) \( (X, Y) \) is defined
\[
G(X, Y) = -\alpha^T X - \beta^T Y - X^T W Y, \quad (4)
\]
where the parameters \( \alpha, \beta, \) and \( W \) are the weights of visible units, hidden units, and those associated with the connection between hidden and visible units, respectively. The probability distributions over hidden or visible vectors in general Boltzmann machines are defined in terms of the energy function [31]:
\[
P(X, Y) = \frac{1}{Z} e^{-G(X, Y)}, \quad (5)
\]
where \( Z \) is a partition function defined as the sum of \( e^{-G(X, Y)} \) over all possible configurations, and the marginal probability of a visible vector is the sum over all possible hidden layer configurations,
\[
P(X) = \frac{1}{Z} \sum_{Y} e^{-G(X, Y)}. \quad (6)
\]
With the restriction that RBM has the shape of a bipartite graph with no intra-layer connections, the hidden unit activations are mutually independent given the visible unit activations, and vice versa. In this paper, we use RBM to pre-train the network layer by layer, and then fine-tune it with feedback method.

B. ARTIFICIAL INTELLIGENCE ALGORITHMS

Artificial intelligence algorithms have been used to predict economic and market behavior [32]–[34]. To compare predictive performances, we focus on three popular artificial neural networks, (i) the back propagation neural network, (ii) the extreme learning machine, and (iii) the radial basis function neural network.

1) BACK PROPAGATION NEURAL NETWORK

The back propagation (BP) neural network is an artificial intelligence algorithm widely used in prediction, in particular for advanced multiple regression analysis. It better generates complex and non-linear responses than a standard regression analysis [35]. The formula for the BP algorithm is
\[
W(n) = W(n-1) - \Delta W(n), \quad (7)
\]
where
\[
\Delta W(n) = \gamma \frac{\partial E}{\partial W}(n-1) + \theta \Delta W(n-1). \quad (8)
\]
Here \( \gamma \) is the learning rate, \( E \) the gradient of error function, and \( \theta \Delta W(n-1) \) the quantity of incremental weight. A BP network uses the gradient method, and the learning and inertial factors are determined by experience. This affects the convergence in a BP network. A BP network rapidly converges to a local minimum, but because it learns the convergent velocity more slowly, it has relatively few applications.

2) EXTREME LEARNING MACHINE

The extreme learning machine (ELM) is a feedforward neural network for classification, regression, clustering, and feature learning with a single layer or multi layers of hidden nodes in which the parameters of hidden nodes need not be tuned. For a set of training samples \( \{(X_j, Z_j)\}_{j=1}^S \) with \( S \) samples and \( V \) classes, the single hidden layer feedforward neural network with \( d \) hidden nodes and activation function \( f \) is
\[
Y_j = \sum_{i=1}^{d} \eta_i f(X_j) = \sum_{i=1}^{d} \eta_i (W_i X_j + e_i), \quad j = 1, 2, \ldots, S, \quad (9)
\]
where \( X_j = [x_{j1}, x_{j2}, \ldots, x_{jd}]^T \) is the input, \( Z_j = [z_{j1}, z_{j2}, \ldots, z_{jV}]^T \) the corresponding output, \( W_i = [w_{i1}, w_{i2}, \ldots, w_{iV}]^T \) the connecting weights of hidden neuron \( i \) to input neurons, \( e_i \) the bias of hidden node \( i \), \( \eta_i = [\eta_{i1}, \eta_{i2}, \ldots, \eta_{iV}]^T \) the connecting weights of hidden neuron \( i \) to the output neurons, and \( Y_j \) the actual network output. Usually the hidden parameters \( \{W_i, e_i\} \) are randomly generated during training without tuning. The ELM solves the compact model using error minimization
\[
\min_{\eta} \|D\eta - Z\|_F, \quad (10)
\]
with

\[ D(W_1, W_2, \ldots, W_d, e_1, e_2, \ldots, e_d) = \begin{bmatrix} f(W_1x_1 + e_1) & \cdots & f(W_hx_1 + e_d) \\ \vdots & \ddots & \vdots \\ f(W_1x_d + e_1) & \cdots & f(W_hx_d + e_d) \end{bmatrix}, \]

\[ \eta = \begin{bmatrix} \eta_1^T \\ \vdots \\ \eta_d^T \end{bmatrix}, \quad Z = \begin{bmatrix} Z_1^T \\ \vdots \\ Z_d^T \end{bmatrix}, \]

where \( D \) is the hidden layer output matrix, and \( \eta \) the output weight matrix. ELM randomly selects the hidden node parameters, and only the output weight parameters needed to be determined. Despite these advantages, ELM cannot be used when the time series is noisy.

3) RADIAL BASIS FUNCTION NEURAL NETWORK

The radial basis function (RBF) network is an artificial neural network that uses radial basis functions for activation. The network output is a linear radial basis function combination of inputs and neuron parameters. RBF networks have many uses, including function approximation, time series prediction, classification, and system control [36]. Radial basis functions are often used to construct function approximations,

\[ y(x) = \sum_{i=1}^{N} \mu_{ij} \varphi(\|x - \mu_j\|), \quad (11) \]

where \( y(x) \) is the sum of \( N \) radial basis functions, and \( \mu_{ij} \) the weight estimated using the linear least square matrix method. The Gaussian function is a commonly used radial basis function, and is here used by \( \varphi(\|x - \mu_j\|) \). Geometrically the RBF network divides the input space into hypersphere subspaces, which can cause such algorithmic problems as overfitting, overtraining, the small-sample effect, and singularities.

III. DATA AND PERFORMANCE EVALUATION CRITERIA

A. DATA

China Securities Index Co., Ltd, a joint venture company of Shanghai and Shenzhen Stock Exchanges, received permission from the China Securities Regulatory Commission to release the China securities indices. The CSI 300 is a representative index of these indices. It is a capitalization-weighted stock market index designed to represent the performance of the top 300 stocks listed in the Shanghai and Shenzhen stock exchanges. As an early stock index futures contract issued in China, the CSI 300 futures contract has enriched the existing index system in China’s securities markets and achieved great success. The CSI 300 index futures began trading on China Financial Futures Exchange (CFFEX) with the commodity ticker symbol IF on 16 April 2010. The notional value of one contract is RMB 300 times the value of the CSI 300. The CSI 300 index futures provides an indicator when observing the fluctuation of the stock market. It facilitates companies and individual investors to better understand stock market developments and allows the accumulation of experience when trading index investment products. Thus we here select the CSI 300 futures contract transaction data for empirical analysis.

The CSI 300 index futures uses the T+0 trading system for short-term transactions. They list the price fluctuations and performance of the Chinese A-share market, which serve as benchmarks for derivative innovations and indexing. Because our goal here is to predict the short-term price of stock index futures and to provide guidance in transactions, the CSI 300 index futures is the appropriate one for analysis.

We collect all transaction data of the CSI 300 futures contract (IF1704) from 20 February 2017 to 20 April 2017, which we acquire from the high frequency RESSET database, a top Chinese financial research data resource. We use one-minute high frequency data that includes opening price, highest price, lowest price, closing price, trade volume, and opening interest to test the performance of deep learning and other artificial intelligence algorithms. We collect 10,000 6-variable groups from 20 February 2017 to 20 April 2017 for a total of 60,000 data.

![FIGURE 3. Opening price per minute of the CSI 300 futures contract (IF1704).](image-url)

Figure 3 shows the minute-by-minute trend of the opening price of the CSI 300 futures contract (IF1704) from 20 February 2017 to 20 April 2017. Note that there is a big fluctuation during this period, and that thus there may be arbitrage opportunities if this indication is accurate.

When using the deep learning algorithm the preparatory data processing includes decreasing the difference between the threshold and the actual data. Usually the sample data are normalized prior to their being input into the neural network,

\[ x_i' = \frac{x_i - x_{min}}{x_{max} - x_{min}}, \quad (12) \]

where \( x_i' \) is the data after normalization, and \( x_{min} \) and \( x_{max} \) the minimum and maximum data of input \( x_i \), respectively. After processing we anti-normalize the output,

\[ \hat{y}_i = \hat{y}_i'y_{max} + y_{min}, \quad (13) \]

where \( \hat{y}_i \) is the predicted data after anti-normalization, and \( y_{min} \) and \( y_{max} \) the minimum and maximum data, respectively, of output \( y_i' \).
B. PERFORMANCE EVALUATION

We use three criteria to evaluate predictive accuracy, (i) the root-mean-square error (RMSE), (ii) the mean absolute percentage error (MAPE), and (iii) the directional predictive accuracy. The RMSE is defined

$$\text{RMSE} = \sqrt{\frac{1}{N} \sum_{t=1}^{N} (\hat{y}_t - y_t)^2},$$

where $y_t$ and $\hat{y}_t$ are actual value and predicted value at time $t$, respectively, and $N$ the data size of the tested set. RMSE expresses the standard deviation of the difference between the predicted and actual values.

The MAPE, also known as the mean absolute percentage deviation (MAPD), expresses the accuracy as a percentage, and is defined

$$\text{MAPE} = \frac{1}{N} \sum_{t=1}^{N} \left| \frac{y_t - \hat{y}_t}{y_t} \right|.$$  

MAPE measures the mean absolute relative error of each prediction model. RMSE and MAPE have been widely used to evaluate the predictive accuracy [37], [38]. The smaller the values of RMSE and MAPE, the higher the accuracy of the model.

Furthermore, we are also interested in tendencies in predictive accuracy, we measure the directional predictive accuracy,

$$\text{DA} = \frac{1}{N} \sum_{t=1}^{N} D_t, \quad D_t = \begin{cases} 1, & (y_{t+1} - y_t)(\hat{y}_{t+1} - y_t) \geq 0, \\ 0, & \text{otherwise}. \end{cases}$$

The closer DA is to 1, the higher the directional predictive accuracy. The closer DA is to 0, the lower the directional predictive accuracy.

IV. RESULTS OF EMPIRICAL ANALYSIS

To eliminate random influences within each simulation we use the average value of 10 simulation results to evaluate the performance of each method. To determine the performance of each neural networks when there are different amounts of data, we divide the database into small, medium and large datasets (see Fig.4). In each small dataset, there are 2000 groups with six variables in each group, yielding a total of 12000 data. There are five small-scale datasets. In each medium dataset, there are 5000 groups with six variables in each group, yielding 30000 data in each medium dataset. There are two medium-scale datasets. Similarly, in each large dataset, there are 10000 groups with 60000 data. We use the first 90 percent of data in each dataset as training samples and the remaining 10 percent as testing samples. We run all neural networks using the Matlab R2017b software package and a Lenovo laptop computer with a Core(TM) i5-5200U 2.20GHz CPU and 8GB of random-access memory (RAM).

In DL the number of hidden layer nodes strongly affects the prediction. There is no uniform way of determining hidden layer nodes [39], and the experience of model creator is key during the layer-by-layer experiment. The number of hidden layer nodes strongly correlates with the input and output layer nodes. In general, the greater the number of nodes in the input and output layers, the greater the number of nodes needed in the hidden layer to achieve efficient feature learning. Currently, the following methods can be used to determine the number of hidden layer nodes,

$$L = \sqrt{m + n + \alpha},$$

and

$$L = \log_2 m,$$

Here $m$ is the number of input layer nodes, $n$ the number of output layer nodes, and $\alpha$ a constant between 1-10. The number of nodes in the hidden layer produced using these methods is only approximate, and often must be corrected during training and learning. Gradually increasing and decreasing the number of hidden layer nodes is a common method of reducing errors to a usable range. We use Eq. (17) to calculate the number of hidden layer nodes and find 10 nodes in the first hidden layer and 4 nodes in the second hidden layer.

A. PREDICTIVE PERFORMANCE OF SMALL-SCALE DATASETS

Each small dataset contains 12000 data. According to the total sample volume, 5 small-scale datasets are obtained for analysis. The first 10800 data (90%) are training data and the remaining 1200 (10%) test data. Figure 5 shows the testing sample values and the CSI 300 futures contract predictions for different periods. Table 1 compares the predictive performances of the DL, BP, ELM and RBF methods. In each dataset we record the average value of 10 simulations. The last line in each period gives the running time for each method, and the last row of Table 1 shows the mean value of each method.
Table 1 shows that the DL prediction of the opening price per minute of the CSI 300 futures contract outperforms the BP, ELM, RBF methods in both accuracy and direction. The mean RMSE value of DL is 1.0437, lower than the mean RMSE values of BP (4.9247), ELM (2.9017), and RBF (2.7788), and the mean MAPE value of DL (0.0002) is also lower than those of BP (0.0013), ELM (0.0007), and RBF (0.0005). Thus the DL method has the lowest error when predicting the price of the CSI 300 index futures. The DL directional prediction of 0.7150 is also more accurate than the mean DA values of BP (0.4650), ELM (0.5100), and RBF (0.6350). The running time for small datasets does not indicate that DL is superior to the other methods. DL usually has more than one hidden layer, thus it requires more time to train the network. These results indicate that the predictive performance of DL is better than that of BP, ELM, and RBF, implying that DL may be a useful tool when forecasting stock market behavior.

Table 2 shows that the DL predictions are superior to those of BP, ELM, and RBF in both accuracy and direction. The DL has a mean RMSE value of 0.7928, much lower than the mean RMSE values of BP (5.1203), ELM (3.2245), and RBF (3.9305). The mean MAPE value of DL is 0.0002,
The error and running time of prediction (large-scale datasets).

<table>
<thead>
<tr>
<th>Testing Period</th>
<th>Criteria</th>
<th>DL</th>
<th>BP</th>
<th>ELM</th>
<th>RBF</th>
</tr>
</thead>
<tbody>
<tr>
<td>4/14 13:01-</td>
<td>RMSE</td>
<td>0.6423</td>
<td>7.6147</td>
<td>1.7071</td>
<td>2.1135</td>
</tr>
<tr>
<td>4/20 13:40</td>
<td>MAPE</td>
<td>0.0001</td>
<td>0.0020</td>
<td>0.0004</td>
<td>0.0002</td>
</tr>
<tr>
<td></td>
<td>DA</td>
<td>0.8120</td>
<td>0.4790</td>
<td>0.5460</td>
<td>0.7870</td>
</tr>
<tr>
<td></td>
<td>Time(s)</td>
<td>26.8537</td>
<td>5.5083</td>
<td>0.4637</td>
<td>3681.4000</td>
</tr>
</tbody>
</table>

Also lower than those of the BP (0.0014), ELM (0.0007), and RBF (0.0009) methods, indicating that the error of DL when predicting the price of the CSI 300 index futures is minimal. The mean DA value of DL is 0.7310 for directional prediction, much higher and more accurate than those of BP (0.4740), ELM (0.5060), and RBF (0.5720). When increasing the size of the sample data, DL also shows better performance. In contrast to the average RBF running time of 218.8905, DL requires on average 11.2566 seconds to complete the training and testing with a usable predictive accuracy. Thus the high predictive performance of DL is also confirmed in medium datasets.

**C. Predictive Performance of Large-Scale Datasets**

Our large-scale dataset contains 60000 data. We use the first 54000 data (90%) to train the network and the remaining 6000 (10%) to test the predictive accuracy of the methods. We have one large-scale dataset in the current database. Figure 7 shows the sample values and the forecasts of the CSI 300 futures contract in the predictive period. Table 3 shows the predictive performances of the DL, BP, ELM, and RBF methods. The average value of 10 simulation results is also provided.

Table 3 shows that the DL predictions of value and direction are more accurate than those of the BP, ELM, and RBF methods. The RMSE value of DL (0.6423) is lower than those of BP (7.6147), ELM (1.7071), and RBF (2.1135). The MAPE value of DL (0.0001) is also lower than those of BP (0.0020), ELM (0.0004), and RBF (0.0002). The error is smallest when using DL to predict the price of the CSI 300 index futures. The DA value of DL (0.8120) is also higher than those of BP (0.4790), ELM (0.5460), and RBF (0.7870), indicating that the deep learning method has the highest directional predictive accuracy. The running time of DL is also superior to that of RBF. Although the DA value of RBF reaches 0.7870, it requires 3681.4000 seconds to process this scale of data. In contrast, DL requires only 26.8537 seconds to process the same data, and the accuracy of its prediction is higher. Thus the predictive performance of DL is better than the others for large-scale dataset.
accuracy, reduces investment blindness, and lowers investment risk.

V. CONCLUSION

Predicting stock market behavior is challenging. Nonlinear relationship among transaction data and unpredictable factors in market fluctuations make predictions difficult. Deep learning is a machine learning method suitable for solving nonlinear approximations that has been successfully applied in many fields.

To achieve better stock market predictive performance, we have used a deep architecture-based model. We use one-minute high frequency transaction data from the CSI 300 futures contract (IF1704) in the Chinese stock market and carry out an empirical analysis. To show the effect of sample volume on network training and predicting, we divide the sample into three scale datasets and compare the stock price prediction of deep learning with three traditional artificial neural networks (BP, ELM, RBF). We compare their predictive fitting degree and directional predictive accuracy and find that the predictive performance of deep learning is superior to that of BP, ELM and RBF. We also find that increasing sample volume significantly increases the predictive performance of deep learning. We thus find that sample volume strongly affects stock prediction, and that deep learning performs well when applied to large data. Furthermore, deep learning does not need prior predictive information to extract features from large datasets, and this increases its usefulness in predicting stock market behavior. This result provides additional evidence that DL is an effective method of predicting stock price. Our deep learning prediction model expands our ability to analyze financial market behavior. Because there are complex relationships among stock futures prices and such factors as the economy, politics, the environment, and culture, future research could apply complex network theory to key input variables that influence stock prices and returns. That would allow the construction of a deep learning network that would facilitate better predictive performance.

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